

Math 343, Lecture 12

① The Boltzmann model

Now

By allowing ourselves this extra freedom

We still require

That is

Let C be a combinatorial class and $C(x)$ its generating function.

Rather than

Suppose $C(x)$ has radius of convergence $\rho > 0$

how plausible is this assumption \rightarrow let's check some examples we've done before

Recall from MACM 201

Def A finite probability space with sample space \mathcal{S} and probability function P , is a finite set \mathcal{S} and a function P from the set of subsets of \mathcal{S} to the interval $[0,1]$ satisfying

$$\textcircled{1} \quad P(A) \geq 0 \quad \forall A \subseteq \mathcal{S}$$

$$\textcircled{2} \quad P(\mathcal{S}) = 1$$

$$\textcircled{3} \quad \begin{array}{l} \text{IF } A, B \subseteq \mathcal{S} \text{ with } A \cap B = \emptyset \\ \text{then } P(A \cup B) = P(A) + P(B) \end{array}$$

take $A = \{a_1, \dots, a_n\} \subseteq \mathcal{S}$. By repeated application of $\textcircled{3}$

$$P(A) =$$

Then we interpret

Combinatorial classes aren't finite, but they're still discrete

so we can define

Def

A discrete probability space with sample space \mathcal{S} and probability function P , is a countable set \mathcal{S} and a function P from the set of subsets of \mathcal{S} to the interval $[0,1]$ satisfying

①

②

③

Note

Evaluating the generating function gives a useful discrete probability space with \mathbb{C} as the sample space

Def

let C_{eff} be a combinatorial class and let $\rho > 0$ be the radius of convergence of $C(x)$.

The Boltzmann model at $0 < x < \rho$ is a discrete probability space with sample space C and probability function given by

$$P_x(c) =$$

lets check that this is a discrete probability space

The other property we wanted was that our probabilities were uniform by size. That is

Proposition

let $\mathcal{C} \neq \emptyset$ be a combinatorial class and
 $0 < x < \rho$ where ρ is the radius of convergence of $C(x)$

let P_x be the probability function for the Boltzmann model.

Suppose

Then

proof

So we know the Boltzmann model is uniform by size
but which sizes are preferred?

Prop let C, ρ, P_x be as above. The expected size

is

$$E_x = x \frac{C'(x)}{C(x)}$$

proof The formula for expected value from probability is

$$E_x =$$

If you didn't know that, you can take the proposition
as a definition of the expected size

Suppose

Then

So our goal is

② Boltzmann samplers

So how do we actually build a Boltzmann sampler?

Let's first start with the class \mathcal{E}

So

Algorithm

Boltzmann ϵ

input x

β is similarly silly :

Algorithm

Boltzmann β

input x

Suppose $A = B + C$ and we have a Boltzmann sampler
for B and C

What is the probability that a generated $a \in A$
came from B ?

Algorithm Boltzmann $A = B + C$

input x

Suppose $A = B \times C$ and suppose we have Boltzmann samplers for A and B

take $a = (b, c) \in A$ $\Rightarrow b \in B$ $c \in C$

then a should be generated with probability



Algorithm Boltzmann $A = B \times C$

input x

eg what about our binary trees

$$T = E + 3 \times T^2$$

We know

This we have

lets try it

(see notes he de other kind
of binary rooted tree)

That kind of worked but

③ What about Sequence?

There are two approaches to sequence

① note

$A = \text{Seq}(B)$ is equivalent to

The cost of this translation is

But there's also a direct way to Boltzmann generators

② Say to generate an element of $\text{Seq } \mathcal{B}$
we first pick a k and then make
 k calls to Boltzmann \mathcal{B}

The question is with what probability should
each k occur?

What do we need?

$$P_x((b_1, \dots, b_k)) =$$

This is a geometric distribution

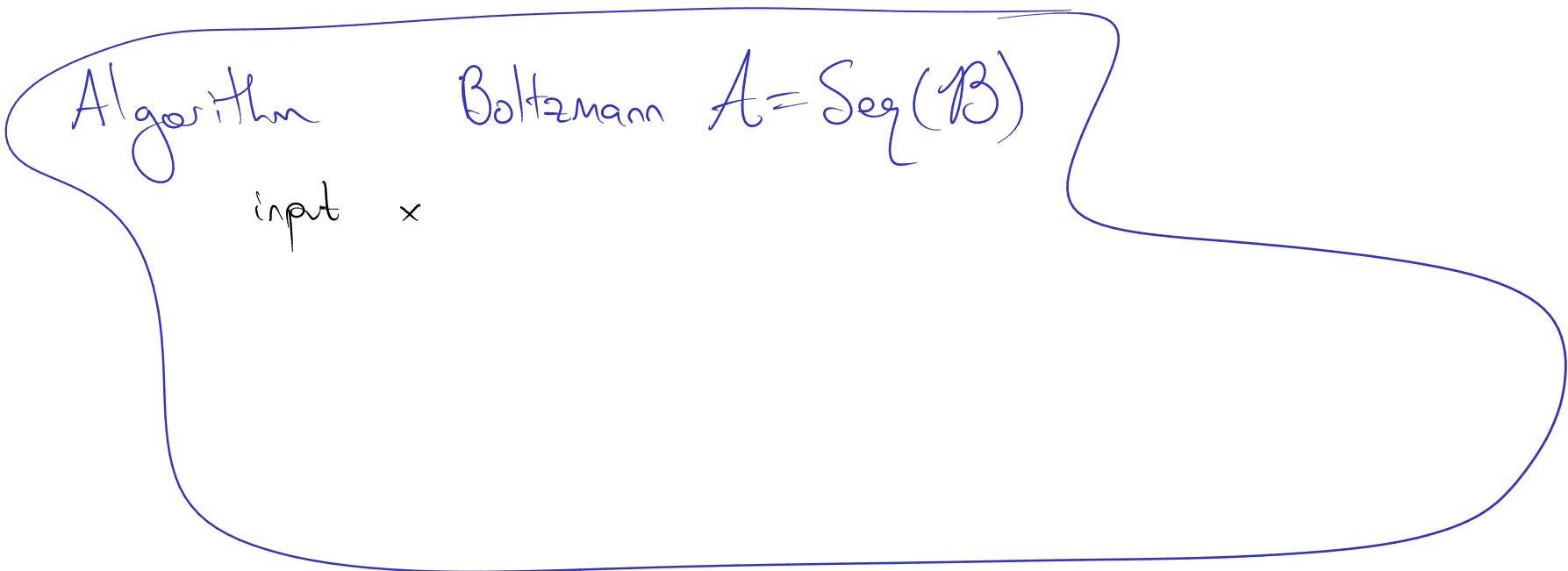
Def The random variable X is **geometrically distributed** if

$$P(X=k) = (1-\lambda)\lambda^k$$

for some $0 < \lambda \leq 1$

How do we know $B(x) \leq 1$?

So assuming we have a geometric random number generator:



④ Next time

Theorems and practicalities

- how to build geometric-rand
- which x to pick
- how fast is Boltzmann generation
- which specifications work well and how to tweak the ones which don't.