

Math 232, Elementary Linear Algebra

J. Hebron, Spring 2000

Final Examination

Tuesday, April 18th, 2000

Time: 3 hours

Student ID Number

Name

(Please underline your family name)

Signature

Instructions:

- Please fill-in the above information in ink.
- Do not open this exam until told to do so.
- No books, no calculators, no cell phones.
- One 8.5 by 11 inch formula sheet (two-sided) allowed.
- The total point value of each problem or part thereof is shown in square brackets.
- Please sign the bottom of every page
(in case your exam becomes unstapled)

Quest. #:	1	2	3	4	5	6	7	8	9	10	11
Mark:											
Out of:	4	3	2	3	6	2	12	12	6	2	8

Quest. #:	12	13	14	15	16	17	18	19	20	21	Tot
Mark:											
Out of:	12	5	15	5	12	16	7	6	4	8	150

[points]

1. Assume that we live in a 3-dimensional subspace of a 7-dimensional Euclidean space, but we are unaware of the other 4 dimensions, until one day an inventor makes a hyperspace ship capable of travelling in the other dimensions. On the maiden voyage, the hyperspace ship travels from $(0,0,0,0,0,0,0)$ to $(2,-3,4,-2,1,-1,1)$ km.
- (a) What is the total distance travelled by the hyperspace ship? [2]
- (b) What is the cosine of the angle between the direction travelled by the hyperspace ship and the x -axis? (Assume the x -axis is in the direction $[1,0,0,0,0,0,0]$.) [2]
2. Let $\vec{a}_1, \vec{a}_2, \dots, \vec{a}_5$ be five non-zero non-parallel vectors in \mathfrak{R}^7 , and let $W = \text{sp}(\vec{a}_1, \vec{a}_2, \dots, \vec{a}_5)$. Suppose W is a 4-dimensional hyperplane in \mathfrak{R}^7 . Explain how this can be. [3]
3. Let \mathbf{A} be a matrix having column vectors $\vec{a}_1, \vec{a}_2, \dots, \vec{a}_k \in \mathfrak{R}^n$, and let $\vec{b} = [b_1, b_2, \dots, b_k] \in \mathfrak{R}^k$. What is $\mathbf{A}\vec{b}$? [2]

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4. Let \mathbf{A} be a matrix having column vectors $\vec{\mathbf{a}}_1, \vec{\mathbf{a}}_2, \dots, \vec{\mathbf{a}}_k \in \mathfrak{R}^n$, and let \mathbf{B} be a matrix having row vectors $\vec{\mathbf{b}}_1, \vec{\mathbf{b}}_2, \dots, \vec{\mathbf{b}}_m \in \mathfrak{R}^n$. Given that $\vec{\mathbf{a}}_i \bullet \vec{\mathbf{b}}_j = 0$ when $i \neq j$, and $\vec{\mathbf{a}}_i \bullet \vec{\mathbf{b}}_i = 1$, what is \mathbf{BA} ? (Assume $k > m$.) [3]

5. (a) What is the elementary matrix which swaps the first and fifth rows of a 7 by 7 matrix? [2]

- (b) What is the elementary matrix which adds 5 times the fifth row of a 5 by 5 matrix to its second row? [2]

- (c) What is the relationship between elementary matrices and invertible matrices? [2]

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6. Let $W = sp(\vec{w}_1, \vec{w}_2, \dots, \vec{w}_7)$, where $\vec{w}_1, \vec{w}_2, \dots, \vec{w}_7 \in \mathfrak{R}^5$, and let \mathbf{A} be the matrix having column vectors $\vec{w}_1, \vec{w}_2, \dots, \vec{w}_7$. Suppose the Row-Echelon form of \mathbf{A} is:

$$\begin{bmatrix} 5 & 3 & 2 & -4 & -2 & 3 & 5 \\ 0 & -3 & 4 & 1 & -2 & 5 & -1 \\ 0 & 0 & 0 & 1 & -4 & -1 & -4 \\ 0 & 0 & 0 & 0 & -2 & -4 & -4 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Find a basis for W .

[2]

7. Let \mathbf{B} be a real n by m matrix and let \mathbf{C} be a real m by n matrix, where $m < n$. Let $\mathbf{A} = \mathbf{BC}$.

(a) Prove: $\text{nullity}(\mathbf{A}) \geq n - m$.

[10]

(b) If \mathbf{A} represents a linear transformation \mathbf{T} , is \mathbf{T} one-to-one? Why or why not?

[2]

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8. The axioms defining an abstract vector space are given as follows:

$$\mathbf{A1:} \quad (\vec{u} + \vec{v}) + \vec{w} = \vec{u} + (\vec{v} + \vec{w}) \qquad \mathbf{S1:} \quad r(\vec{v} + \vec{w}) = r\vec{v} + r\vec{w}$$

$$\mathbf{A2:} \quad \vec{v} + \vec{w} = \vec{w} + \vec{v} \qquad \mathbf{S2:} \quad (r + s)\vec{v} = r\vec{v} + s\vec{v}$$

$$\mathbf{A3:} \quad \vec{0} + \vec{v} = \vec{v} \qquad \mathbf{S3:} \quad r(s\vec{v}) = (rs)\vec{v}$$

$$\mathbf{A4:} \quad \vec{v} + (-\vec{v}) = \vec{0} \qquad \mathbf{S4:} \quad 1\vec{v} = \vec{v}$$

The set \mathfrak{R}^2 with a weird vector addition " \oplus " defined by:

$$[x, y] \oplus [a, b] = [x + a + q, y + b],$$

and a weird scalar multiplication defined by:

$$r[x, y] = [rx + rq - q, ry],$$

where q is a real constant, is a vector space.

(a) Verify axioms **A3**, **A4**, and **S4**.

[10]

(b) Note $r[0, 0] = [rq - q, 0] \neq [0, 0]$. Does this contradict the theorem that $r\vec{0} = \vec{0}$?
Why or why not?

[2]

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9. (a) Give an example of a vector space \mathbf{V} which is not finitely generated. What is its basis?
(Before answering this question, read parts (b) and (c).) [2]
- (b) Give an example of a proper subspace of \mathbf{V} which is also not finitely generated. What is its basis? [2]
- (c) Give an example of a proper subspace of \mathbf{V} which is finitely generated. What is its basis? [2]
10. Can an n -dimensional vector space be isomorphic to an m -dimensional vector space, where $m \neq n$? Explain. [2]

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11. Let a polynomial $p(x)$ be defined by the by the following determinant:

$$p(x) = \begin{vmatrix} 1 & a_1 & a_1^2 & a_1^3 & \cdots & a_1^n \\ 1 & a_2 & a_2^2 & a_2^3 & \cdots & a_2^n \\ 1 & a_3 & a_3^2 & a_3^3 & \cdots & a_3^n \\ \vdots & \vdots & \vdots & \vdots & & \vdots \\ 1 & a_n & a_n^2 & a_n^3 & \cdots & a_n^n \\ 1 & x & x^2 & x^3 & \cdots & x^n \end{vmatrix}$$

where $a_i \in \mathfrak{R}$ and $a_i \neq a_j$ when $i \neq j$

(a) What is the order of $p(x)$? Explain your answer. [3]

(b) What are the roots of $p(x)$? Explain your answers. [5]

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12. Let $\mathbf{T}: \mathfrak{R}^n \rightarrow \mathfrak{R}^n$ be a linear transformation which rotates \mathfrak{R}^n by an angle of $1/2$ radian about the line passing through the origin in the direction $[1, 2, 3, 4, \dots, n]$, and let \mathbf{A} be the standard matrix representation of \mathbf{T} .

(a) What are the real eigenvalues and corresponding eigenspaces of \mathbf{A} ? Explain your answers.

[6]

(b) What are the real eigenvalues and corresponding eigenspaces of \mathbf{A}^m , where m is any integer ≥ 2 ? Explain.

[3]

(c) Is \mathbf{A} an orthogonal matrix? Why or why not?

[3]

(Signature)

13. Find the orthogonal complement to the subspace W of \mathfrak{R}^3 defined by $ax + by + cz = 0$, where $a, b, c \in \mathfrak{R}$ are constants and $x, y, z \in \mathfrak{R}$ are variables.

[5]

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14. Let $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$ be a non-orthogonal set of k independent vectors in \mathfrak{R}^n , where $k < n$. You are asked to expand this set to form a basis for \mathfrak{R}^n . The basis must include $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$, so it will not be an orthogonal basis and therefore you can't use the Gram-Schmidt process.

(a) Suppose you want the basis to be composed of $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$ and $n - k$ standard basis vectors \hat{e}_j . How would you go about finding this basis?

[5]

(b) Let W be the k -dimensional subspace of \mathfrak{R}^n spanned by $(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k)$, and let W^\perp be its orthogonal complement. In general, the $n - k$ standard basis vectors found in part (a) will not span W^\perp . Suppose you want to find a different basis for \mathfrak{R}^n composed of $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$ and $n - k$ vectors which span W^\perp . How would you go about finding this basis?

[5]

(c) Let $\vec{b} = [b_1, b_2, \dots, b_n]$ be a vector in \mathfrak{R}^n . How would you find the projection of \vec{b} onto W ?

[5]

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15. Let M_3^u be the vector space of upper triangular real 3 by 3 matrices, and suppose you have an ordered basis given by:

$$B = \left(\begin{bmatrix} a_1 & a_6 & a_5 \\ 0 & a_2 & a_4 \\ 0 & 0 & a_3 \end{bmatrix}, \begin{bmatrix} b_1 & b_6 & b_5 \\ 0 & b_2 & b_4 \\ 0 & 0 & b_3 \end{bmatrix}, \begin{bmatrix} c_1 & c_6 & c_5 \\ 0 & c_2 & c_4 \\ 0 & 0 & c_3 \end{bmatrix}, \begin{bmatrix} d_1 & d_6 & d_5 \\ 0 & d_2 & d_4 \\ 0 & 0 & d_3 \end{bmatrix}, \begin{bmatrix} f_1 & f_6 & f_5 \\ 0 & f_2 & f_4 \\ 0 & 0 & f_3 \end{bmatrix}, \begin{bmatrix} g_1 & g_6 & g_5 \\ 0 & g_2 & g_4 \\ 0 & 0 & g_3 \end{bmatrix} \right)$$

Let \vec{v} be a vector in M_3^u given by $\vec{v} = \begin{bmatrix} v_1 & v_6 & v_5 \\ 0 & v_2 & v_4 \\ 0 & 0 & v_3 \end{bmatrix}$.

How would you go about finding \vec{v}_B ?

[5]

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16. Let $i = \sqrt{-1}$.

(a) What is $\frac{1}{i}$?

[1]

(b) Using Euler's formula, find the three cube roots of -8, in polar form $(re^{i\theta})$, and plot them in the complex plane.

[8]

(c) Convert the answers to part (b) into the form $a + ib$, where $a, b \in \mathfrak{R}$.

[3]

(Signature)

17. Let the matrix \mathbf{A} be defined by:

$$\mathbf{A} = \begin{bmatrix} \frac{3}{2} & \frac{1}{2} & 0 & 0 \\ -\frac{1}{2} & \frac{1}{2} & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 1 & 1 \end{bmatrix}$$

(a) Find all the eigenvalues of \mathbf{A} , including the complex ones, and their algebraic multiplicities.

[10]

(b) For all eigenvalues which have an algebraic multiplicity greater than 1, find the corresponding eigenspaces and their geometric multiplicities.

[4]

(c) Is \mathbf{A} diagonalizable? Explain.

[2]

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18. Let \mathbf{A} be an orthogonal n by n matrix and let $\vec{\mathbf{x}}$ and $\vec{\mathbf{y}}$ be any column vectors in \mathfrak{R}^n .

(a) Prove $(\mathbf{A}\vec{\mathbf{x}}) \bullet (\mathbf{A}\vec{\mathbf{y}}) = \vec{\mathbf{x}} \bullet \vec{\mathbf{y}}$.

[3]

(b) Prove $\|\mathbf{A}\vec{\mathbf{x}}\| = \|\vec{\mathbf{x}}\|$.

[2]

(c) Prove the angle between $\vec{\mathbf{x}}$ and $\vec{\mathbf{y}}$ is the same as the angle between $\mathbf{A}\vec{\mathbf{x}}$ and $\mathbf{A}\vec{\mathbf{y}}$.

[2]

(Signature)

19. Suppose you have a computational algorithm which processes large amounts of measured data. Let the data be placed into a vector $\bar{\mathbf{x}}$ in \mathfrak{R}^n and let \mathbf{A} be an n by n matrix which multiplies $\bar{\mathbf{x}}$ in the computation. What is the advantage of orthogonalizing the computational algorithm so that \mathbf{A} is an orthogonal matrix?

[6]

20. The projection matrix \mathbf{P} for the subspace W of \mathfrak{R}^n spanned by the column vectors of \mathbf{A} is given by $\mathbf{P} = \mathbf{A}(\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T$. What's wrong with the following argument?
 $\mathbf{A}(\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T = \mathbf{A}(\mathbf{A}^{-1}(\mathbf{A}^T)^{-1})\mathbf{A}^T = (\mathbf{A}\mathbf{A}^{-1})(\mathbf{A}^T)^{-1} \mathbf{A}^T = (\mathbf{I})(\mathbf{I}) = \mathbf{I}$, and therefore $\mathbf{P} = \mathbf{I}$.
Explain your reasoning.

[4]

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21. Let $V = \text{sp}(e^{-x}, 1, e^x)$ be a subspace of the vector space of continuous functions of one variable, and let $B = (e^{-x}, 1, e^x)$ be an ordered basis for V . Let $B' = (\cosh(x), \sinh(x), 1)$ be another ordered basis for V . What is the change of coordinates matrix $C_{B, B'}$?

[8]

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