

MATH 821, SPRING 2012, ASSIGNMENT 3 SOLUTIONS

(1) First we have a trilinear map

$$f : V_1 \times V_2 \times V_3 \rightarrow V_1 \otimes (V_2 \otimes V_3)$$

given by $f(v_1, v_2, v_3) = v_1 \otimes (v_2 \otimes v_3)$. Fixing any value v_3 in the third component $f(\cdot, \cdot, v_3)$ is bilinear and so by the universal property of tensor products we have a linear map

$$\phi_{v_3} : V_1 \otimes V_2 \rightarrow V_1 \otimes (V_2 \otimes V_3)$$

given by $\phi_{v_3}(v_1 \otimes v_2) = f(v_1, v_2, v_3) = v_1 \otimes (v_2 \otimes v_3)$.

Now consider

$$g : (V_1 \otimes V_2) \times V_3 \rightarrow V_1 \otimes (V_2 \otimes V_3)$$

given by $g(v, v_3) = \phi_{v_3}(v)$ for $v \in V_1 \otimes V_2$. Since f was linear in the third coordinate, g is linear in the third coordinate when applied to pure tensors and hence always. g is linear in the first coordinate since ϕ_{v_3} is linear for each v_3 . Thus g is bilinear and so by the universal property of tensor products we have a linear map

$$\psi : (V_1 \otimes V_2) \otimes V_3 \rightarrow V_1 \otimes (V_2 \otimes V_3)$$

given by $\psi((v_1 \otimes v_2) \otimes v_3) = v_1 \otimes (v_2 \otimes v_3) = f(v_1, v_2, v_3)$. The same argument with the parenthesization the other way gives the inverse map and hence this is an isomorphism proving the result.

(2) Let $f, g, h \in \text{Hom}(A, A)$. Then

$$\begin{aligned} (f \star g) \star h &= \cdot((f \star g) \otimes h)\Delta \\ &= \cdot(\cdot \otimes \text{Id})(f \otimes g \otimes h)(\Delta \otimes \text{Id})\Delta \\ &= \cdot(\text{Id} \otimes \cdot)(f \otimes g \otimes h)(\text{Id} \otimes \Delta)\Delta \\ &= f \star (g \star h) \end{aligned}$$

by associativity of \cdot and coassociativity of Δ . Also

$$\begin{aligned} f \star (u \circ \epsilon) &= \cdot(f \otimes (u \circ \epsilon))\Delta \\ &= \cdot(\text{Id} \otimes u)(f \otimes \text{Id})(\text{Id} \otimes \epsilon)\Delta \\ &= f \end{aligned}$$

by the unit and counit properties, and similarly on the other side

$$\begin{aligned} (u \circ \epsilon) \star f &= \cdot((u \circ \epsilon) \otimes f)\Delta \\ &= \cdot(u \otimes \text{Id})(\text{Id} \otimes f)(\epsilon \otimes \text{Id})\Delta \\ &= f \end{aligned}$$

So $\text{Hom}(A, A)$ is an algebra under the convolution product.

- (3) There are a number of ways to approach this. Here's the very explicit approach, probably not the prettiest, but you just do it:

Let S° be the antipode of H° , and similarly for the other structure functions.

Let $\{a_i\}$ be a basis of H with $a_0 = 1$ and $\{f_i\}$ the dual basis of H° . Let $\Delta(a_i) = \sum_{j,k} c_{j,k}^{(i)} a_j \otimes a_k$ and $a_j \cdot a_k = \sum_i d_{j,k}^{(i)} a_i$. We know from class that $\Delta^\circ(f_i) = \sum_{j,k} d_{j,k}^{(i)} f_j \otimes f_k$ and $f_j \cdot^\circ f_k = \sum_i c_{j,k}^{(i)} f_i$.

Write $S^\circ(a_i) = \sum_\ell e_\ell^{(i)} a_\ell$. Then

$$\cdot(S \otimes \text{Id})\Delta = u \circ \epsilon$$

so for $i > 0$

$$0 = \cdot(S \otimes \text{Id})\Delta(a_i) = \sum_{j,k,\ell,m} d_{\ell,k}^{(m)} e_\ell^{(j)} c_{j,k}^{(i)} a_m$$

so since the a_i form a basis

$$(1) \quad \sum_{j,k,\ell,m} d_{\ell,k}^{(m)} e_\ell^{(j)} c_{j,k}^{(i)} = 0$$

I claim that $S^\circ = S^*$ (where $S^*(f)(a) = f(S(a))$ as usual). Note that $S^*(f_i)(a_j) = f_i(S(a_j)) = e_i^{(j)}$ so $S^*(f_i) = \sum_j e_i^{(j)} f_j$.

Since H is graded and connected we also know that H° is graded and connected, so S° is uniquely defined by satisfying

$$\cdot^\circ(S^\circ \otimes \text{Id})\Delta^\circ = u^\circ \circ \epsilon^\circ$$

Consider this with S^* on the dual basis. For $f_0 = \text{Id}$ we have

$$\text{Id} = u^\circ(\epsilon^\circ(f_0))$$

and

$$\cdot^\circ(S^* \otimes \text{Id})\Delta^\circ(f_0) = S^*(\text{Id}) = \text{Id}$$

as desired. For $i > 0$ we have

$$0 = u^\circ(\epsilon^\circ(f_i))$$

and

$$\cdot^\circ(S^* \otimes \text{Id})\Delta^\circ(f_i) = \sum_{j,k,\ell,m} c_{\ell,k}^{(m)} e_j^{(\ell)} d_{j,k}^{(i)} f_m = 0$$

by (1), which proves the result.

- (4) See handwritten pages appended.

- (5) See <http://loic.foissy.free.fr/pageperso/preprint3.pdf>

$$\begin{aligned}
 a) \quad \Delta(\text{diagram}) &= \text{diagram} \otimes \mathbb{1} + \mathbb{1} \otimes \text{diagram} + 2 \cdot \text{diagram} \otimes \text{diagram} + 2 \cdot \text{diagram} \\
 &+ \dots \otimes \text{diagram} + \dots \otimes \text{diagram} + 4 \cdot \dots \otimes \text{diagram} + 2 \cdot \dots \otimes \text{diagram} + 2 \cdot \dots \otimes \text{diagram} \\
 &+ \dots \otimes \text{diagram} + \text{diagram} \otimes \text{diagram} + 2 \cdot \text{diagram} \cdot \text{diagram} \otimes \text{diagram} + \text{diagram} \cdot \text{diagram} \otimes \text{diagram} \\
 &+ \text{diagram} \otimes \text{diagram} + 2 \cdot \text{diagram} \otimes \text{diagram} + \dots \cdot \text{diagram} \otimes \text{diagram}.
 \end{aligned}$$

$$\begin{aligned}
 b) \quad \Delta(\text{diagram}) &= \text{diagram} \otimes \mathbb{1} + \mathbb{1} \otimes \text{diagram} + 2 \cdot \text{diagram} \otimes \text{diagram} + \dots \otimes \text{diagram} + 2 \cdot \text{diagram} \otimes \text{diagram} \\
 S(\cdot) &= -\cdot \\
 S(\mathbb{1}) &= -\mathbb{1} - S(\cdot) = -\mathbb{1} + \dots \\
 S(\text{diagram}) &= -\text{diagram} - 2S(\cdot) \otimes \text{diagram} - S(\cdot) \otimes \text{diagram} - 2S(\mathbb{1}) \otimes \text{diagram} - 2S(\mathbb{1}) \otimes \text{diagram} \\
 &= -\text{diagram} + 2 \cdot \text{diagram} - \dots \otimes \text{diagram} + 2 \cdot \text{diagram} \otimes \text{diagram} - 2 \cdot \text{diagram} \otimes \text{diagram} - 2 \cdot \text{diagram} \otimes \text{diagram} \\
 &\quad - \text{diagram} \otimes \text{diagram} + 2 \cdot \text{diagram} \otimes \text{diagram} - \dots \otimes \text{diagram} \\
 &= -\text{diagram} + 2 \cdot \text{diagram} - \dots \otimes \text{diagram} + 2 \cdot \text{diagram} \otimes \text{diagram} - 2 \cdot \text{diagram} \otimes \text{diagram} - 3 \cdot \text{diagram} \otimes \text{diagram} + 4 \cdot \text{diagram} \otimes \text{diagram} - \dots
 \end{aligned}$$

c) A basis for all elements of order 3 is $\{ \cdot, \wedge, \cdot \cdot, \cdot \cdot \cdot, \dots \}$
 calculate the nonprimitive parts of the coproducts of each

$$\tilde{\Delta}(\cdot) = \cdot \otimes 1 + 1 \otimes \cdot$$

$$\tilde{\Delta}(\wedge) = 2 \cdot \otimes \cdot + \cdot \cdot \otimes \cdot$$

$$\tilde{\Delta}(\cdot \cdot) = \cdot \otimes \cdot + \cdot \cdot \otimes \cdot + 1 \otimes \cdot + \cdot \otimes \cdot \cdot$$

$$\tilde{\Delta}(\cdot \cdot \cdot) = 3 \cdot \otimes \cdot \cdot + 3 \cdot \cdot \otimes \cdot$$

Every linear combination of these equaling 0 gives a primitive element and every primitive element can be built in this way

No such linear combination can involve $\tilde{\Delta}(\wedge)$ since the other three are all commutative but it is not. By inspection the only nontrivial linear combinations of the others giving 0 are

$$3a \tilde{\Delta}(\cdot) + a \tilde{\Delta}(\cdot \cdot \cdot) - 3a \tilde{\Delta}(\cdot \cdot), \quad a e k^*$$

So the primitive elements of degree 3 are

$$3a \cdot + a \cdot \cdot \cdot - 3a \cdot \cdot, \quad a e k^*$$