

A) BUSINESS

- paper assignment due: MON 08 SEPT
- online " " : THU 11 SEPT

B) LAST 3AY

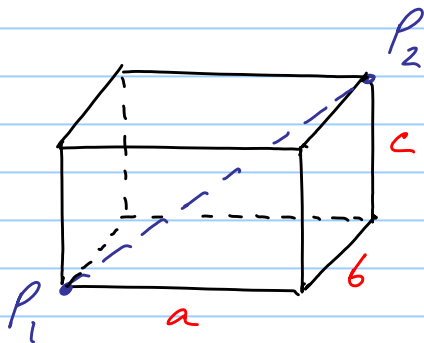
- coordinates of a point in 3 dimensions: $P = (x, y, z)$
- sets of points & equations of surfaces

$$S_1 = \{ (x, y, z) \mid x=0, y=0 \} \rightarrow$$

$$S_2 = \{ (x, y) \mid x+y=1 \} \rightarrow$$

$$S_3 = \{ (x, y, z) \mid x+y=1 \} \rightarrow$$

- length of diagonal of a box



$$|P_1 P_2| = \sqrt{a^2 + b^2 + c^2}$$

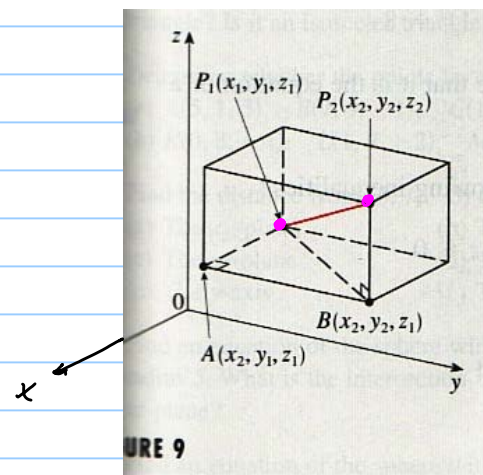
by repetitive use of
Pythagorean formula.
(WES notes)

c) DISTANCE FORMULA FOR 2 POINTS

- 2 points in \mathbb{R}^3 define the opposite corners of a rectangular box

$$P_1 = (x_1, y_1, z_1)$$

$$P_2 = (x_2, y_2, z_2)$$



$$\begin{aligned} \text{side in } x\text{-direction} &= |P_1 A| \\ &= | \quad | \end{aligned}$$

$$\begin{aligned} \text{and } |AB| &= | \quad | \\ |BP_2| &= | \quad | \end{aligned}$$

$$\begin{aligned} |P_1 P_2| &= \sqrt{\quad^2 + \quad^2 + \quad^2} \\ &= \sqrt{\quad^2 + \quad^2 + \quad^2} \end{aligned}$$

p.767

5) WHAT IS THE SET OF POINTS WHOSE DISTANCE FROM $C = (h, k, l)$ IS r ($r > 0$)?

$$(a) \quad S = \left\{ (x, y, z) \mid \sqrt{(\quad)^2 + (\quad)^2 + (\quad)^2} = r \right\}$$

$$\text{OR } S = \left\{ (x, y, z) \mid \underbrace{(x-h)^2 + (y-k)^2 + (z-l)^2 = r^2} \right\}$$

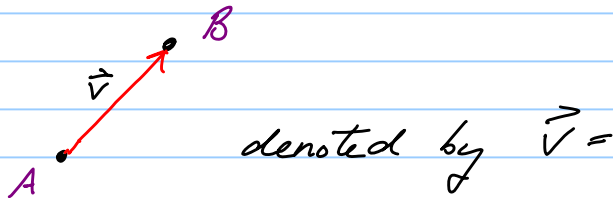
(b) a **SPHERE** of radius r centred at the point $C = (h, k, l)$

equation for a sphere in $\mathbb{R}^3 \rightarrow$ spherical surface

- read examples 5 & 6 (p768) "the contour" via inequality

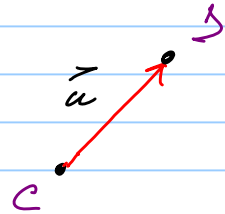
E) VECTORS (12.2)

- a **vector** is a geometrical quantity that has both magnitude and direction. It is represented by an arrow (or directed line segment) in space.



- although represented as an arrow from the initial point A to the terminal point B , only the relative displacement is important.

as we say the vectors \vec{v} & \vec{u} are equal.

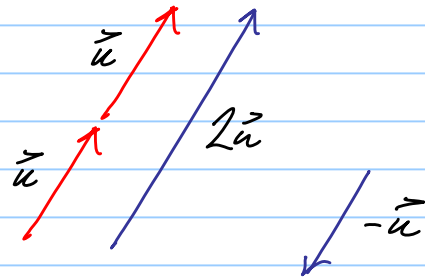
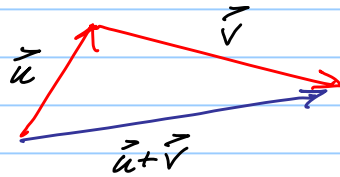


- vectors are NOT associated with any fixed point or location in space

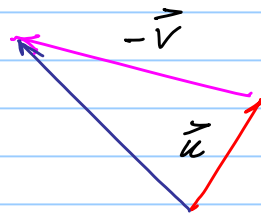
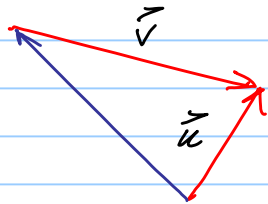
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F) ARITHMETIC NATURE OF VECTORS (p 770-772)

- vectors can be added & scalar multiplied



scalar multiply: same orientation, magnitude is multiplied by a real number



=

- magnitude of a vector =

Properties of Vectors If \mathbf{a} , \mathbf{b} , and \mathbf{c} are vectors in V_n and c and d are scalars, then

1. $\mathbf{a} + \mathbf{b} = \mathbf{b} + \mathbf{a}$	2. $\mathbf{a} + (\mathbf{b} + \mathbf{c}) = (\mathbf{a} + \mathbf{b}) + \mathbf{c}$
3. $\mathbf{a} + \mathbf{0} = \mathbf{a}$	4. $\mathbf{a} + (-\mathbf{a}) = \mathbf{0}$
5. $c(\mathbf{a} + \mathbf{b}) = c\mathbf{a} + c\mathbf{b}$	6. $(c + d)\mathbf{a} = c\mathbf{a} + d\mathbf{a}$
7. $(cd)\mathbf{a} = c(d\mathbf{a})$	8. $1\mathbf{a} = \mathbf{a}$

(p 774)

G) ALGEBRAIC NATURE OF VECTORS (p772-

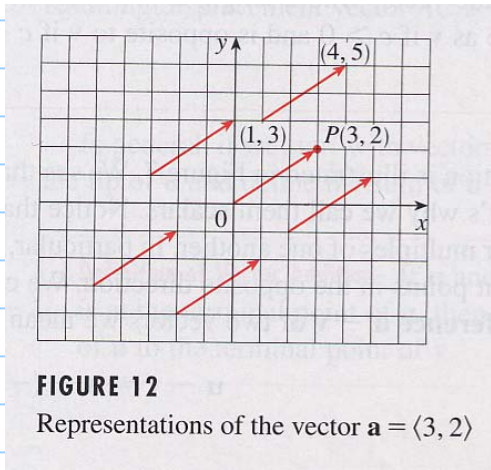


FIGURE 12
Representations of the vector $\mathbf{a} = \langle 3, 2 \rangle$

- embed vector in coordinate system
- place initial point at
- denote vector by coordinates of arrowhead. $\vec{a} =$
- works in \mathbb{R}^2 + \mathbb{R}^3

WARNING: do not confuse POINTS + VECTORS

- both can be uniquely identified by coordinates, but are distinct concepts
- for a 3D vector having initial point $A = (x_1, y_1, z_1)$ + arrow point $B = (x_2, y_2, z_2)$

$$\vec{AB} = \langle \quad , \quad , \quad \rangle \quad (\text{p773})$$

- magnitude formula for $\vec{u} = \langle a, b, c \rangle \in \mathbb{R}^3$

$$|\vec{u}| = \sqrt{\quad}$$

multiplicity of rotation

$$|a| =$$

$$|P_1 P_2| =$$

$$|\vec{a}| =$$

If $\mathbf{a} = \langle a_1, a_2 \rangle$ and $\mathbf{b} = \langle b_1, b_2 \rangle$, then

$$\mathbf{a} + \mathbf{b} = \langle a_1 + b_1, a_2 + b_2 \rangle \quad \mathbf{a} - \mathbf{b} = \langle a_1 - b_1, a_2 - b_2 \rangle$$

$$c\mathbf{a} = \langle ca_1, ca_2 \rangle$$

Similarly, for three-dimensional vectors,

$$\langle a_1, a_2, a_3 \rangle + \langle b_1, b_2, b_3 \rangle = \langle a_1 + b_1, a_2 + b_2, a_3 + b_3 \rangle$$

$$\langle a_1, a_2, a_3 \rangle - \langle b_1, b_2, b_3 \rangle = \langle a_1 - b_1, a_2 - b_2, a_3 - b_3 \rangle$$

$$c\langle a_1, a_2, a_3 \rangle = \langle ca_1, ca_2, ca_3 \rangle$$

- special vectors (\mathbb{R}^3)

$$\vec{0} = \text{zero vector} = \langle \quad, \quad, \quad \rangle$$

unit basis vectors: $\hat{i} = \langle \quad, \quad, \quad \rangle$

$|\hat{i}| = 1$, etc

$$\hat{j} = \langle \quad, \quad, \quad \rangle$$

$$\hat{k} = \langle \quad, \quad, \quad \rangle$$

$$\vec{a} = \langle x_1, y_1, z_1 \rangle = \underbrace{\quad \hat{i} + \quad \hat{j} + \quad \hat{k}}_{\text{scalar mult.}}$$

H) APPLICATIONS

- quantifying geometry (magnitude & direction)
- familiar vectors of physics

VELOCITY

$$\vec{\text{ground speed}} = \vec{\text{wind speed}} + \vec{\text{air speed}} \quad (\#30)$$

FORCE

- i) net force on an object is the sum of all applied forces (vectors) (#28)
- ii) the forces acting on a stationary object sum (as vectors) to zero (vector)
(ex 7, p776 & #34)