

# Orthogonality

The idea of orthogonality plays a central role in many branches of mathematics and its applications.

## Vector Space

A vector space  $V$  (over the reals) consists of elements ("vectors") eg  $\vec{u}, \vec{v} \in V$

together with a chosen field of scalars  $s, t \in \mathbb{R}$

(we consider only real-valued vectors, functions etc ;  
in general could have eg complex numbers, but our scalars will be real numbers)

such that  $V$  is closed under addition and scalar multiplication

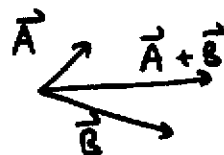
$$\text{ie } \vec{u} + \vec{v} \in V, s\vec{u} \in V \quad \text{for all } \vec{u}, \vec{v} \in V, s, t \in \mathbb{R}$$
$$(\Rightarrow s\vec{u} + t\vec{v} \in V)$$

with the properties:

- Associativity:  $\vec{u} + (\vec{v} + \vec{w}) = (\vec{u} + \vec{v}) + \vec{w}$
- Commutativity:  $\vec{u} + \vec{v} = \vec{v} + \vec{u}$
- Zero vector  $\vec{0}$ :  $\vec{u} + \vec{0} = \vec{0} + \vec{u} = \vec{u}$
- Inverse vector:  $\vec{u} + (-\vec{u}) = (-\vec{u}) + \vec{u} = \vec{0}$
- Distributivity:  $s(\vec{u} + \vec{v}) = s\vec{u} + s\vec{v}$   
 $(s+t)\vec{u} = s\vec{u} + t\vec{u}$
- Zero scalar 0:  $0 \vec{u} = \vec{0}$
- Unit scalar 1:  $1 \vec{u} = \vec{u}$

Examples:

- Vectors in  $\mathbb{R}^2$ :



Vectors in  $\mathbb{R}^3$

Vectors in  $\mathbb{R}^n$  (n-tuples),  $\vec{A}, \vec{B}, \dots \in \mathbb{R}^n$

- Set of quadratic polynomials (degree  $\leq 2$ )  
 $a_0 + a_1 x + a_2 x^2$ ,  $a_0, a_1, a_2 \in \mathbb{R}$

(sum of two quadratic polynomials is a quadratic polynomial;  
 so is any multiple of a quadratic polynomial  
 by a real number)

More generally: set  $P_n$  of polynomials of degree  $\leq n$ :

$$a_0 + a_1 x + a_2 x^2 + \dots + a_n x^n, \quad a_0, a_1, a_2, \dots, a_n \in \mathbb{R}$$

- Set of continuous functions on  $[-1, 1]$   $\leftarrow$  more generally,  $[a, b]$   
 $f, g \in C[-1, 1]$ ,  $s, t \in \mathbb{R}$

$$\Rightarrow sf + tg \in C[-1, 1]$$

- Set of functions on  $[a, b]$  vanishing at the endpoints  
 $f(a) = f(b) = 0$

## Basis

A set of linearly independent elements of  $V$  so that each element ("vector") of  $V$  can be written as a linear combination of basis elements

### Linear combination:

Let  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n \in V$ .  $\vec{u}$  is a linear combination of the  $\{\vec{v}_i\}$  if there are scalars  $t_1, t_2, \dots, t_n \in \mathbb{R}$  so that

$$\vec{u} = t_1 \vec{v}_1 + t_2 \vec{v}_2 + \dots + t_n \vec{v}_n = \sum_{i=1}^n t_i \vec{v}_i$$

### Linear independence:

The vectors  $\{\vec{v}_i\}$  are linearly independent if the only solution of

$$t_1 \vec{v}_1 + t_2 \vec{v}_2 + \dots + t_n \vec{v}_n = \sum_{i=1}^n t_i \vec{v}_i = \vec{0}$$

is  $t_1 = t_2 = \dots = t_n = 0$

(no nontrivial linear combination adds to  $\vec{0}$ ; equivalently, none of the  $\vec{v}_i$  is a linear combination of the others)

-else they are linearly dependent.

Fact: If one basis of the vector space  $V$  has a finite number  $N$  of elements, then every basis has  $N$  elements; then  $V$  is an  $N$ -dimensional vector space.

eg in  $\mathbb{R}^2$  (a two-dimensional space: every basis has 2 elements)

$\hat{i}, \hat{j}$  forms a basis

Another basis:  $\vec{a}_1 = \hat{i} + 2\hat{j}$ ,  $\vec{a}_2 = 3\hat{i} - \hat{j}$

eg in the set of quadratic polynomials  $P_2$ :

$\{1, x, x^2\}$  form a basis

(since every quadratic polynomial is  $a_0 \cdot 1 + a_1 \cdot x + a_2 \cdot x^2$ )

$\Rightarrow P_2$  is a 3-dimensional vector space.

Similarly  $P_n$ , the space of  $n^{\text{th}}$  degree polynomials, is an  $(n+1)$ -dimensional vector space, with basis  $\{1, x, \dots, x^n\}$

## Inner Product (Scalar product, "Dot Product")

of two elements ("vectors") of  $V$

is a scalar (real), denoted  $(\vec{u}, \vec{v})$  or  $\vec{u} \cdot \vec{v}$

conventional notation for functions

convention for vectors  $\in \mathbb{R}^n$

satisfying (for real vector space)

- $(\vec{u}, \vec{v}) \in \mathbb{R}$

- $(\vec{u}, \vec{v}) = (\vec{v}, \vec{u})$

- Linearity  $(s\vec{u}_1 + t\vec{u}_2, \vec{v}) = s(\vec{u}_1, \vec{v}) + t(\vec{u}_2, \vec{v})$

- $(\vec{u}, \vec{u}) \geq 0$

- $(\vec{u}, \vec{u}) = 0 \Leftrightarrow \vec{u} = \vec{0}$  in  $V$

ie  $(\vec{u}, \vec{u}) > 0$  for all nonzero vectors  $\vec{u} \in V$

eg for vectors in  $\mathbb{R}^2$ :  $\vec{v}_1 = a_1 \hat{i} + a_2 \hat{j}$ ,  $\vec{v}_2 = b_1 \hat{i} + b_2 \hat{j}$   
 $\Rightarrow (\vec{v}_1, \vec{v}_2) = \vec{v}_1 \cdot \vec{v}_2 = a_1 b_1 + a_2 b_2$

vectors in  $\mathbb{R}^n$ :  $\vec{v} = a_1 \hat{e}_1 + a_2 \hat{e}_2 + \dots + a_n \hat{e}_n = \sum_{i=1}^n a_i \hat{e}_i$   
 $\vec{w} = b_1 \hat{e}_1 + b_2 \hat{e}_2 + \dots + b_n \hat{e}_n$

$\{\hat{e}_1, \hat{e}_2, \dots, \hat{e}_n\}$ : orthonormal basis  
 eg Cartesian basis

$$\Rightarrow \vec{v} \cdot \vec{w} = a_1 b_1 + \dots + a_n b_n = \sum_{i=1}^n a_i b_i$$

### Norm

Given an inner product, we can define the "length" / "magnitude" of a vector - the norm:

$$\|\vec{v}\| = [\vec{v} \cdot \vec{v}]^{1/2} = [(\vec{v}, \vec{v})]^{1/2}$$

Note:  $\|\vec{v}\| \in \mathbb{R}$

$$\|\vec{v}\| > 0 \text{ if } \vec{v} \neq \vec{0}, \quad \|\vec{0}\| = 0$$

eg for vectors in  $\mathbb{R}^n$ ,  $\|\vec{v}\| = \left( \sum_{i=1}^n a_i^2 \right)^{1/2}$  (Pythagoras' Theorem)  
 $\|\vec{v}\|$   $\leftarrow$  Euclidean norm

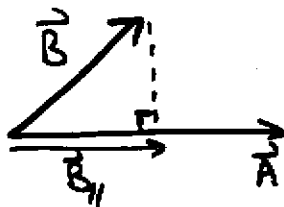
### Orthogonality

Two nonzero vectors  $\vec{u}, \vec{v} \in V$  are orthogonal

if  $(\vec{u}, \vec{v}) = 0$ .

## Consequence of Orthogonality:

Recall: projection



$$\hat{A} = \frac{\vec{A}}{|\vec{A}|}$$

$$\vec{B}_{\parallel} = \frac{\vec{B} \cdot \vec{A}}{|\vec{A}|^2} \vec{A} = \underbrace{(\vec{B} \cdot \hat{A})}_{\text{comp}_{\vec{A}} \vec{B}} \hat{A} = \text{proj}_{\vec{A}} \vec{B}$$

Suppose an element of  $V$  is expanded in terms of orthogonal basis elements; then we can easily find the expansion coefficients by projection

(ie taking inner/dot products)

eg for vectors in  $\mathbb{R}^3$ :

Let  $\{\vec{b}_1, \vec{b}_2, \vec{b}_3\}$  be any set of mutually

orthogonal vectors

$$(\vec{b}_i \cdot \vec{b}_j = 0 \text{ for } i \neq j)$$

$\Rightarrow$  they form a basis of  $V = \mathbb{R}^3$  (independent).

For any vector  $\vec{u}$ , we can write

$$\vec{u} = t_1 \vec{b}_1 + t_2 \vec{b}_2 + t_3 \vec{b}_3$$

Since the  $\{\vec{b}_i\}$  are orthogonal, find the coefficients  $t_i$

by projection:

$$\begin{aligned} \vec{u} \cdot \vec{b}_1 &= t_1 \vec{b}_1 \cdot \vec{b}_1 + t_2 \underbrace{\vec{b}_2 \cdot \vec{b}_1}_{=0} + t_3 \underbrace{\vec{b}_3 \cdot \vec{b}_1}_{=0} \\ &= t_1 \vec{b}_1 \cdot \vec{b}_1 + 0 + 0 \end{aligned}$$

$$\Rightarrow t_1 = \frac{\vec{u} \cdot \vec{b}_1}{\vec{b}_1 \cdot \vec{b}_1}$$

$$\text{Similarly } t_2 = \frac{\vec{u} \cdot \vec{b}_2}{\vec{b}_2 \cdot \vec{b}_2}, \quad t_3 = \frac{\vec{u} \cdot \vec{b}_3}{\vec{b}_3 \cdot \vec{b}_3}$$

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and 
$$\vec{u} = \sum_{j=1}^3 \underbrace{\left( \frac{\vec{u} \cdot \vec{b}_j}{\vec{b}_j \cdot \vec{b}_j} \right)}_{t_j} \vec{b}_j = \text{proj}_{\vec{b}_1} \vec{u} + \text{proj}_{\vec{b}_2} \vec{u} + \text{proj}_{\vec{b}_3} \vec{u}$$

Note: from an orthogonal basis, we can construct an orthonormal basis (of mutually orthogonal unit vectors)

by  $\hat{e}_i = \frac{\vec{b}_i}{|\vec{b}_i|}$ , then  $\hat{e}_i \cdot \hat{e}_j = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases} = \delta_{ij}$

In this case, the expansion coefficients are:

$$\vec{u} = s_1 \hat{e}_1 + s_2 \hat{e}_2 + s_3 \hat{e}_3$$

$$\Rightarrow \vec{u} \cdot \hat{e}_1 = s_1 \underbrace{\hat{e}_1 \cdot \hat{e}_1}_{=1} + 0 + 0 = s_1, \quad \begin{matrix} s_2 = \vec{u} \cdot \hat{e}_2 \\ s_3 = \vec{u} \cdot \hat{e}_3 \end{matrix}$$

In general, if  $\{\vec{b}_1, \vec{b}_2, \dots, \vec{b}_N\}$  are  $N$  mutually orthogonal vectors:

$$\vec{u} = t_1 \vec{b}_1 + \dots + t_N \vec{b}_N = \sum_{j=1}^N t_j \vec{b}_j$$

$$\rightarrow \vec{u} \cdot \vec{b}_i = \sum_{j=1}^N t_j \underbrace{\vec{b}_j \cdot \vec{b}_i}_{=0 \text{ if } i \neq j} = t_i \vec{b}_i \cdot \vec{b}_i \quad \leftarrow \text{projection of } \vec{u} \text{ onto } i\text{th basis element, using orthogonality}$$

$$\Rightarrow t_i = \frac{\vec{u} \cdot \vec{b}_i}{\vec{b}_i \cdot \vec{b}_i}, \quad i=1, \dots, N$$

# Gram-Schmidt Orthogonalization

Given a set of independent elements of  $V$ , we can construct an orthogonal set by the Gram-Schmidt process

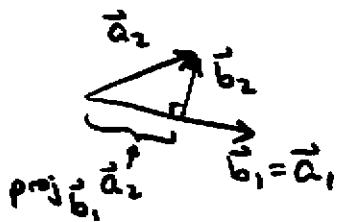
eg for vectors in  $\mathbb{R}^N$

- Assume  $\{\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n\}$  are independent.

Start with  $\vec{b}_1 = \vec{a}_1$

Now find  $\vec{b}_2 \in \text{span}\{\vec{a}_1, \vec{a}_2\}$ , orthogonal to  $\vec{b}_1$ ,  
by starting with  $\vec{a}_2$  and subtracting the component  
in the direction of  $\vec{b}_1$ .

$$\vec{b}_2 = \vec{a}_2 - \text{proj}_{\vec{b}_1} \vec{a}_2 = \vec{a}_2 - \frac{\vec{a}_2 \cdot \vec{b}_1}{\vec{b}_1 \cdot \vec{b}_1} \vec{b}_1$$



$$\text{(check: } \vec{b}_2 \cdot \vec{b}_1 = \vec{a}_2 \cdot \vec{b}_1 - \left(\frac{\vec{a}_2 \cdot \vec{b}_1}{\vec{b}_1 \cdot \vec{b}_1}\right) \vec{b}_1 \cdot \vec{b}_1 = 0 \text{)}$$

Continue similarly:

$$\vec{b}_3 = \vec{a}_3 - \text{proj}_{\vec{b}_1} \vec{a}_3 - \text{proj}_{\vec{b}_2} \vec{a}_3 = \vec{a}_3 - \sum_{i=1}^2 \frac{\vec{a}_3 \cdot \vec{b}_i}{\vec{b}_i \cdot \vec{b}_i} \vec{b}_i$$

$$\vdots$$

$$\vec{b}_k = \vec{a}_k - \underbrace{\sum_{j=1}^{k-1} \left( \frac{\vec{a}_k \cdot \vec{b}_j}{\vec{b}_j \cdot \vec{b}_j} \right) \vec{b}_j}_{\text{proj}_{\vec{b}_j} \vec{a}_k}$$

projection of  $\vec{a}_k$  onto subspace  
spanned by  $\{\vec{b}_1, \vec{b}_2, \dots, \vec{b}_{k-1}\}$

$$\left[ \text{Check that } \vec{b}_k \text{ is orthogonal to } \vec{b}_i \quad 1 \leq i < k \quad : \text{ (assume } \{\vec{b}_1, \dots, \vec{b}_{k-1}\} \text{ orthogonal)} \right.$$

$$\vec{b}_k \cdot \vec{b}_i = \vec{a}_k \cdot \vec{b}_i - \sum_{j=1}^{k-1} \left( \frac{\vec{a}_k \cdot \vec{b}_j}{\vec{b}_j \cdot \vec{b}_j} \right) \underbrace{\vec{b}_j \cdot \vec{b}_i}_{=0, j \neq i}$$

$$= \vec{a}_k \cdot \vec{b}_i - \frac{\vec{a}_k \cdot \vec{b}_i}{\vec{b}_i \cdot \vec{b}_i} \vec{b}_i \cdot \vec{b}_i = 0 \quad \left. \right]$$



eg given  $\vec{a}_1 = \hat{i} + 2\hat{j}$  ,  $\vec{a}_2 = 3\hat{i} - \hat{j}$  :

Gram-Schmidt:  $\vec{b}_1 = \vec{a}_1 = \hat{i} + 2\hat{j}$

$$\begin{aligned} \vec{b}_2 &= \vec{a}_2 - \text{proj}_{\vec{b}_1} \vec{a}_2 = (3\hat{i} - \hat{j}) - \frac{\vec{a}_2 \cdot \vec{b}_1}{\vec{b}_1 \cdot \vec{b}_1} (\hat{i} + 2\hat{j}) \\ &= (3\hat{i} - \hat{j}) - \frac{1}{5} (\hat{i} + 2\hat{j}) = \frac{14}{5} \hat{i} - \frac{7}{5} \hat{j} \\ &= \frac{7}{5} (2\hat{i} - \hat{j}) \end{aligned}$$

- clearly  $\vec{b}_1 \cdot \vec{b}_2 = 0$ .

Orthonormal set:  $\hat{e}_1 = \frac{\vec{b}_1}{|\vec{b}_1|} = \frac{1}{\sqrt{5}} (\hat{i} + 2\hat{j})$ ,  $\hat{e}_2 = \frac{\vec{b}_2}{|\vec{b}_2|} = \frac{1}{\sqrt{5}} (2\hat{i} - \hat{j})$

This general approach is appropriate to any vector space  $V$  with an inner product  $(\cdot, \cdot)$  :

- construct orthogonal basis by Gram-Schmidt process
- expand in orthogonal basis by projection (taking inner products).

Inner Products for Functions :

A vector  $\vec{A}$  in  $\mathbb{R}^N$   $\leftarrow$  ( $N$ -dimensional space) is completely described by  $N$  values

$A_i$  ,  $i=1, \dots, N$  (the components of  $\vec{A}$  wrt. an orthonormal (Cartesian) basis).

Suppose the number of dimensions  $\rightarrow$  infinity  
vectors  $\rightarrow$  (continuous) functions  $\leftarrow$  (assume)

- a function  $f$  is described by its values  $f(x)$  at infinitely many points  $x$ .

Inner product of vectors  $\vec{A}, \vec{B}$  is  $\vec{A} \cdot \vec{B} = \sum_{i=1}^N A_i B_i$

As  $N \rightarrow \infty$ , the sum in the inner product  $\rightarrow$  integral.

This motivates:

Consider functions on an interval  $[a, b]$ . (real-valued)

Define an inner product for functions:

$$(f, g) = \int_a^b f(x) g(x) dx$$

(Check that this satisfies the requirements for inner products: linearity,  $(f, f) \geq 0$ ,  $(f, g) = (g, f)$   
 $(f, f) = \int_a^b f^2 dx = 0 \Leftrightarrow f(x) \equiv 0$ .)

Functions  $f, g$  are orthogonal on  $[a, b]$

$$\text{if } (f, g) = \int_a^b f(x) g(x) dx = 0.$$

Sometimes it is convenient to introduce a weight function

$w(x) > 0$   
 or  $f(x) \rightarrow$

(sometimes one can allow  $w(x) \geq 0$ ,  
 with  $w=0$  possibly at isolated points)

-then define a weighted inner product

$$(f, g)_w = \int_a^b f(x) g(x) w(x) dx$$

# Legendre Polynomials

Consider polynomials on  $[-1, 1]$  (ie  $a = -1, b = 1$ )  
with inner product  $(f, g) = \int_{-1}^1 f(x) g(x) dx$ .

Basis of polynomials :  $1, x, x^2, x^3, \dots$

(eg the polynomials  $1, x, x^2, x^3$  are linearly independent, form a basis for  $P_3$ , the 4-dimensional space of cubic polynomials, polynomials of degree  $\leq 3$ )

Note: the polynomials  $1, x$  are orthogonal:

$$(1, x) = \int_{-1}^1 1 \cdot x dx = \frac{1}{2} x^2 \Big|_{-1}^1 = 0$$

but in general, this basis is not orthogonal w.r.t.

this inner product eg  $1, x^2$  are not orthogonal:

$$(1, x^2) = \int_{-1}^1 1 \cdot x^2 dx = \frac{1}{3} x^3 \Big|_{-1}^1 = \frac{2}{3} \neq 0.$$

Apply Gram-Schmidt process to

$$f_0 = 1, f_1 = x, f_2 = x^2, f_3 = x^3, \dots$$

to obtain an orthogonal set (w.r.t the given inner product):

•  $p_0(x) = f_0(x) = 1$

<p>• <math>p_1(x) = f_1(x) - \frac{(f_1, p_0)}{(p_0, p_0)} p_0(x)</math></p> <p><math>= x - \frac{(x, 1)}{(1, 1)}</math></p> <p><math>= x</math></p>	<p><math>(1, 1) = \int_{-1}^1 1^2 dx = 2</math></p> <p><math>(x, 1) = \int_{-1}^1 x \cdot 1 dx = 0</math></p>
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$$\begin{aligned}
 \bullet \quad p_2(x) &= f_2(x) - \sum_{j=0}^1 \frac{(f_2, p_j)}{(p_j, p_j)} p_j(x) \\
 &= x^2 - \frac{(x^2, 1)}{(1, 1)} \cdot 1 - \frac{(x^2, x)}{(x, x)} x \\
 &= x^2 - \frac{2/3}{2} \cdot 1 - \frac{0}{2/3} x \\
 &= x^2 - 1/3
 \end{aligned}$$

$$(x^2, 1) = \int_{-1}^1 x^2 \cdot 1 dx = \frac{2}{3}$$

$$(x^2, x) = \int_{-1}^1 x^2 \cdot x dx = 0$$

$$(x, x) = \int_{-1}^1 x^2 dx = \frac{2}{3}$$

$$(x^3, 1) = \int_{-1}^1 x^3 \cdot 1 dx = 0$$

$$(x^3, x) = \int_{-1}^1 x^3 \cdot x dx = \frac{2}{5}$$

$$(x^3, p_2) = \int_{-1}^1 x^3 (x^2 - 1/3) dx = 0$$

$$\begin{aligned}
 \bullet \quad p_3(x) &= f_3(x) - \sum_{j=0}^2 \frac{(f_3, p_j)}{(p_j, p_j)} p_j(x) \\
 &= x^3 - \frac{(x^3, 1)}{(1, 1)} \cdot 1 - \frac{(x^3, x)}{(x, x)} x - \frac{(x^3, p_2)}{(p_2, p_2)} p_2(x) \\
 &= x^3 - 0 - \frac{2/5}{2/3} x - 0 \\
 &= x^3 - \frac{3}{5} x
 \end{aligned}$$

⋮

- can continue this process to obtain higher degree polynomials.

Note: •  $p_n(x)$  is a polynomial of degree  $n$

• The polynomials  $\{p_n(x)\}$  are orthogonal w.r.t. the given inner product:

$$(p_m, p_n) = \int_{-1}^1 p_m(x) p_n(x) dx = 0 \quad \text{if } m \neq n$$

•  $p_n(x)$  is even if  $n$  is even, odd if  $n$  odd  
ie  $p_n(-x) = (-1)^n p_n(x)$

Usually normalize the polynomials to obtain  $P_n(x) = a_n p_n(x)$   
so that  $P_n(1) = 1$

- gives the Legendre polynomials

$$P_0(x) = 1$$

$$P_1(x) = x$$

$$P_2(x) = \frac{1}{2}(3x^2 - 1)$$

$$P_3(x) = \frac{1}{2}(5x^3 - 3x)$$

⋮

• Each  $P_k(x)$  is a linear combination of  $x^j$ ,  $j \leq k$ ,  
 $P_k(x)$  independent

⇒  $x^k$  is a linear combination of  $P_j(x)$ ,  $j \leq k$

$\{P_0(x), P_1(x), \dots, P_n(x)\}$  forms a basis (orthogonal!)

for  $P_n[-1, 1]$ , the vector space of polynomials of  
degree  $\leq n$  on  $[-1, 1]$

↑  $(n+1)$ -dimensional  
- any  $(n+1)$  independent elements  
form a basis

• If  $q(x)$  is a polynomial of degree  $n$ , then

expansion in  
orthogonal  
basis

$$\rightarrow q(x) = \sum_{j=0}^n c_j P_j(x) = c_0 P_0(x) + \dots + c_n P_n(x)$$

and the coefficients  $c_j$  can be found by projection:

$$(q, P_i) = \sum_{j=0}^n c_j \underbrace{(P_j, P_i)}_{=0 \text{ if } i \neq j} = c_i (P_i, P_i)$$

$$\Rightarrow c_i = \frac{(q, P_i)}{(P_i, P_i)} = \frac{\int_{-1}^1 q(x) P_i(x) dx}{\int_{-1}^1 P_i^2(x) dx}$$

## Approximation by Legendre Polynomials

If  $f(x)$  is a function on  $[-1, 1]$ , then

$$F_n(x) = \sum_{j=0}^n \frac{(f, P_j)}{(P_j, P_j)} P_j(x)$$

is an approximation of  $f$  by polynomials of degree  $\leq n$ .

eg  $n=0$ :

$$F_0(x) = \frac{(f, P_0)}{(P_0, P_0)} P_0(x) = \frac{1}{2} \left[ \int_{-1}^1 f(x) dx \right] \cdot 1 \quad \left| \begin{array}{l} P_0 = 1 \\ (P_0, P_0) = 2 \end{array} \right.$$

$$= \underbrace{\frac{1}{2} \int_{-1}^1 f(x) dx}_{C_0} \quad \text{average of } f \text{ on } [-1, 1]$$

$n=1$ :

$$F_1(x) = \frac{(f, P_0)}{(P_0, P_0)} P_0(x) + \frac{(f, P_1)}{(P_1, P_1)} P_1(x) \quad \left| \begin{array}{l} P_1 = x \\ (P_1, P_1) = \int_{-1}^1 x^2 dx \\ = 2/3 \end{array} \right.$$

$$= F_0(x) + \frac{3}{2} \underbrace{\left[ \int_{-1}^1 x f(x) dx \right]}_{C_1} x$$

$$= C_0 + C_1 x$$

- a linear approximation of  $f$  over the entire interval  $[-1, 1]$ .

[Note: one can show

$$(P_n, P_n) = \int_{-1}^1 P_n(x)^2 dx = \frac{2}{2n+1}, \quad n = 0, 1, 2, \dots$$

$$\Rightarrow (P_m, P_n) = \frac{2}{2n+1} \delta_{mn}$$

normalization

## Comparison with Taylor Polynomials

Recall: Linear approximation of  $f$  near  $x = x_0$ :

Approximate  $f(x)$  by  $T_1(x) = f(x_0) + f'(x_0)(x - x_0)$

tangent line to graph of  $f$  at  $x = x_0$   
 - best linear approximation to  $f(x)$  near  $x_0$

Compare: the approximation by Legendre polynomials is an approximation over the entire interval  $[-1, 1]$

Similarly:  $n^{\text{th}}$  degree Taylor polynomial

$$T_n(x) = f(x_0) + f'(x_0)(x - x_0) + \frac{1}{2} f''(x_0)(x - x_0)^2 + \dots + \frac{1}{n!} f^{(n)}(x_0)(x - x_0)^n = \sum_{j=0}^n \frac{f^{(j)}(x_0)(x - x_0)^j}{j!}$$

- a good local approximation to  $f$ , near  $x_0$

Note: Taylor polynomial uses information about  $f$  and its derivatives at a single point  $x_0$

- good locally, not necessarily globally.

Legendre polynomial approximation

$$F_n(x) = \sum_{j=0}^n \frac{\int_{-1}^1 f(x) P_j(x) dx}{\int_{-1}^1 P_j(x)^2 dx} P_j(x)$$

uses information about  $f(x)$  on the entire interval  $[-1, 1]$  (from integrals of  $f$ ): a global approximation

Legendre polynomials have many other properties and applications, such as:

Facts . Rodrigues' Formula 
$$P_n(x) = \frac{1}{2^n n!} \frac{d^n}{dx^n} (x^2-1)^n,$$
  
 $n=0,1,2,\dots$

• Recurrence relations - a Legendre polynomial at one point  $x$  can be expressed by neighbouring Legendre polynomials at  $x$

$$\text{eg } (n+1)P_{n+1}(x) = (2n+1)xP_n(x) - nP_{n-1}(x), \quad n=1,2,3,\dots$$

(allows one to compute all  $P_n(x)$  from  $P_0=1, P_1=x$ )  
 - and several other similar relations

• Differential equation  $P_n(x)$  solves Legendre's differential equation

$$(1-x^2)\frac{d^2P_n}{dx^2} - 2x\frac{dP_n}{dx} + n(n+1)P_n = 0$$

- numerous applications, such as in numerical analysis

(integration formulas, approximation) and differential equations, especially to the solution of problems (eg Laplace's equation)

in spherical coordinates (with  $x = \cos \phi$ )

Given a different interval  $[a,b]$  and/or a different

weight function  $p(x)$  (inner product  $(f,g)_p = \int_a^b p(x)f(x)g(x)dx$ )

we get a different set of orthogonal polynomials, with different properties and applications

eg on  $[-1,1]$ ,  $p(x) = \frac{1}{\sqrt{1-x^2}}$  : Chebyshev polynomials

$(-\infty, \infty)$ ,  $p(x) = e^{-x^2}$  : Hermite polynomials

$[0, \infty)$ ,  $p(x) = e^{-x}$  : Laguerre polynomials



## Trigonometric Approximation and Fourier Series

Many processes in science and engineering are periodic, or have oscillatory properties (eg heartbeat, waves, signals)  
 - would like to approximate them by periodic functions

Basic building blocks: Sinusoids (sine, cosine) with different frequencies form the basic oscillatory functions (simple harmonic oscillations):

the functions

$\cos 0x$   $\rightarrow$  1,  $\cos x$ ,  $\sin x$ ,  $\cos 2x$ ,  $\sin 2x$ , ...,  $\cos kx$ ,  $\sin kx$ , ...  
 are all  $2\pi$ -periodic.

We wish to approximate a function  $f(x)$  with a superposition of trigonometric functions  $\uparrow$  on the interval  $[-\pi, \pi]$  of length  $2\pi$

$$f(x) \approx F_n(x) = a_0 + a_1 \cos x + a_2 \cos 2x + \dots + a_n \cos nx \\ + b_1 \sin x + b_2 \sin 2x + \dots + b_n \sin nx$$

$$\Rightarrow F_n(x) = a_0 + \sum_{k=1}^n [a_k \cos kx + b_k \sin kx]$$

$F_n(x)$ : trigonometric polynomial of degree  $n$   
 (Fourier polynomial)

$a_k, b_k$ : Fourier coefficients

How do we find the coefficients  $a_k, b_k$  ?

Fundamental property:

The functions

$1, \cos x, \sin x, \cos 2x, \sin 2x, \dots, \cos kx, \sin kx, \dots$   
are orthogonal on  $[-\pi, \pi]$ , with respect to the  
inner product  $(f, g) = \int_{-\pi}^{\pi} f(x)g(x)dx$ .

Orthogonality conditions:

$$\int_{-\pi}^{\pi} \cos mx \cos nx dx = \begin{cases} 2\pi & m=n=0 \\ \pi & m=n \neq 0 \\ 0 & m \neq n \end{cases}$$

$$\int_{-\pi}^{\pi} \sin mx \sin nx dx = \begin{cases} \pi & m=n \\ 0 & m \neq n \end{cases} = \pi \delta_{mn}$$

$$\int_{-\pi}^{\pi} \cos mx \sin nx dx = 0 \quad \begin{matrix} m=0, 1, 2, 3, \dots \\ n=1, 2, 3, \dots \end{matrix}$$

Check using trigonometric identities

$$\text{eg } \int_{-\pi}^{\pi} \sin mx \sin nx dx = \frac{1}{2} \int_{-\pi}^{\pi} [\cos(m-n)x - \cos(m+n)x] dx$$

$$= \begin{cases} \text{(for } m \neq n, m, n = 1, 2, 3, \dots) \\ \frac{1}{2} \left[ \frac{1}{m-n} \sin(m-n)x - \frac{1}{m+n} \sin(m+n)x \right] \Big|_{-\pi}^{\pi} = 0 \\ \text{(for } m = n = 1, 2, 3, \dots) \\ \frac{1}{2} \left[ x - \frac{1}{m+n} \sin(m+n)x \right] \Big|_{-\pi}^{\pi} = \pi \end{cases}$$

Due to the orthogonality, the expansion

$$f(x) \approx F_n(x) = a_0 + \sum_{k=1}^n [a_k \cos kx + b_k \sin kx]$$

is an orthogonal expansion, and we can find the Fourier coefficients by projection (taking inner products):

inner product with  $1 = \cos 0x$  →

$$(f, 1) = a_0 (1, 1) + \sum_{k=1}^n [a_k \underbrace{(\cos kx, 1)}_{=0} + b_k \underbrace{(\sin kx, 1)}_{=0}]$$

$$= a_0 (1, 1)$$

$$\Rightarrow a_0 = \frac{(f, 1)}{(1, 1)} = \frac{\int_{-\pi}^{\pi} 1 \cdot f(x) dx}{\int_{-\pi}^{\pi} 1^2 dx} = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(x) dx$$

$1 \leq m \leq n$

$$(f, \cos mx) = a_0 \underbrace{(1, \cos mx)}_{=0} + \sum_{k=1}^n [a_k \underbrace{(\cos kx, \cos mx)}_{=0 \text{ for } k \neq m} + b_k \underbrace{(\sin kx, \cos mx)}_{=0}]$$

$$= a_m (\cos mx, \cos mx)$$

$$\Rightarrow a_m = \frac{(f, \cos mx)}{(\cos mx, \cos mx)} = \frac{\int_{-\pi}^{\pi} f(x) \cos mx dx}{\int_{-\pi}^{\pi} \cos^2 mx dx} \leftarrow \pi$$

$1 \leq m \leq n$

$$(f, \sin mx) = a_0 \underbrace{(1, \sin mx)}_{=0} + \sum_{k=1}^n [a_k \underbrace{(\cos kx, \sin mx)}_{=0} + b_k \underbrace{(\sin kx, \sin mx)}_{=0 \text{ for } m \neq k}]$$

$$= b_m (\sin mx, \sin mx)$$

$$\Rightarrow b_m = \frac{(f, \sin mx)}{(\sin mx, \sin mx)} = \frac{\int_{-\pi}^{\pi} f(x) \sin mx dx}{\int_{-\pi}^{\pi} \sin^2 mx dx} \leftarrow \pi$$

Thus the coefficients in the trigonometric (Fourier) expansion

$$f(x) \approx F_n(x) = a_0 + \sum_{k=1}^n [a_k \cos kx + b_k \sin kx]$$

are given by:

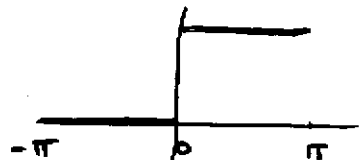
Fourier coefficients

$$a_0 = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(x) dx \quad \leftarrow \text{average of } f \text{ on } [-\pi, \pi]$$

$$a_k = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \cos kx dx$$

$$b_k = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \sin kx dx$$

eg square wave (period  $2\pi$ )

$$f(x) = \begin{cases} 0 & -\pi \leq x < 0 \\ 1 & 0 \leq x \leq \pi \end{cases}$$


( $2\pi$ -periodic extension



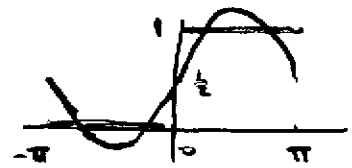
$$a_0 = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(x) dx = \frac{1}{2\pi} \int_0^{\pi} 1 dx = \frac{1}{2}$$

$$a_k = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \cos kx dx = \frac{1}{\pi} \int_0^{\pi} \cos kx dx = \frac{1}{\pi k} \sin kx \Big|_0^{\pi} = 0$$

$$\begin{aligned} b_k &= \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \sin kx dx = \frac{1}{\pi} \int_0^{\pi} \sin kx dx = -\frac{1}{\pi k} \cos kx \Big|_0^{\pi} \\ &= \frac{1}{\pi k} (1 - \cos k\pi) = \frac{1}{\pi k} (1 - (-1)^k) = \begin{cases} 0 & k \text{ even} \\ \frac{2}{\pi k} & k \text{ odd} \end{cases} \end{aligned}$$

Fourier polynomial of degree 1:

$$f(x) \approx F_1(x) = \frac{1}{2} + \frac{2}{\pi} \sin x$$



Fourier polynomial of degree 3:

$$f(x) \approx F_3(x) = \frac{1}{2} + \frac{2}{\pi} \sin x + \frac{2}{3\pi} \sin 3x$$



- a better approximation

Higher-degree approximations: ( $n$  odd)

$$f(x) \approx F_n(x) = \frac{1}{2} + \sum_{\substack{k=1 \\ k \text{ odd}}}^n \frac{2}{\pi k} \sin kx$$

Higher-degree Fourier approximations are more accurate.

Continue procedure, letting  $n \rightarrow \infty$ :

Fourier series for the square wave

$$\begin{aligned} F(x) &= \frac{1}{2} + \frac{2}{\pi} \sin x + \frac{2}{3\pi} \sin 3x + \frac{2}{5\pi} \sin 5x + \dots \\ &= \frac{1}{2} + \sum_{\substack{k=1 \\ k \text{ odd}}}^{\infty} \frac{2}{k\pi} \sin kx \end{aligned}$$

(We don't consider here the important and difficult question of convergence of this infinite series.)

In this case, the series converges pointwise to the square wave  $f(x)$  at each  $x$  except at the points of discontinuity  $x = 0, \pm\pi$ .)

Fourier series: uses information about  $f$  on entire interval (via integrals); good global approximation of function (Taylor series: local approximation)