

A bifurcation - qualitative change in the character of solutions of a nonlinear system as a parameter is varied

In applications, models have parameters

eg buckling beam



weight m : control parameter

deflection: dynamical variable x

(spontaneous symmetry breaking)

Bifurcations of fixed points:

Flow on a line $\dot{x} = f(x) = f_r(x) = f(x, r)$

r : parameter(s)

Fixed point $x^*(r)$: $f(x^*(r), r) = 0$

Bifurcation point r_c :

A parameter value $r=r_c$ so that an arbitrarily small change in the parameter results in topologically distinct phase portraits and qualitatively different behaviour

- at r_c , system is structurally unstable

Structural stability: all "sufficiently close" systems have the same qualitative behaviour

- need hyperbolic fixed points, $f'(x^*, r) \neq 0$

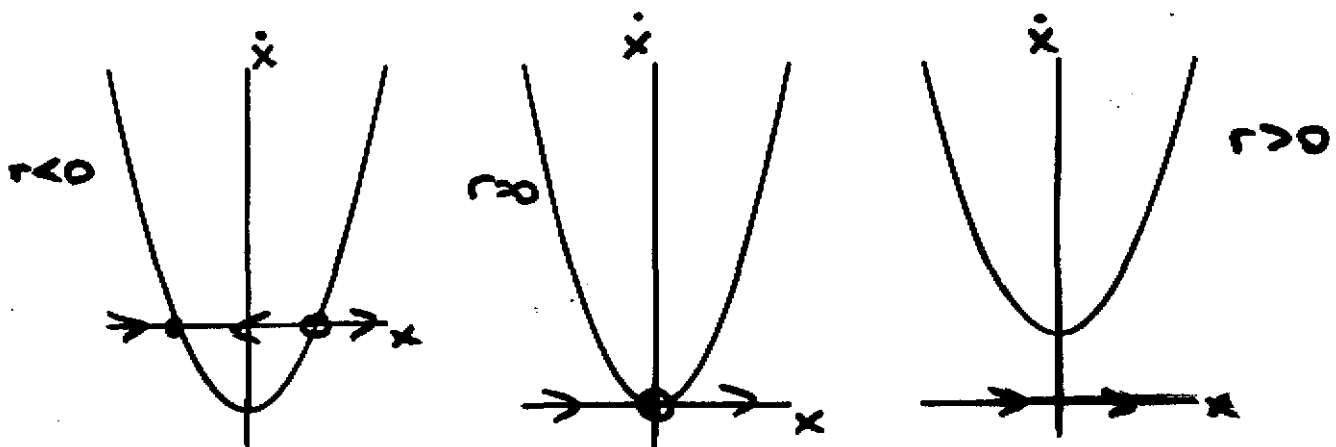
Saddle-Node Bifurcation

- creation and destruction of fixed points

Prototypical example:

$$\dot{x} = r + x^2$$

r : bifurcation parameter



$r < 0$: Fixed points $x^* = \pm \sqrt{-r}$

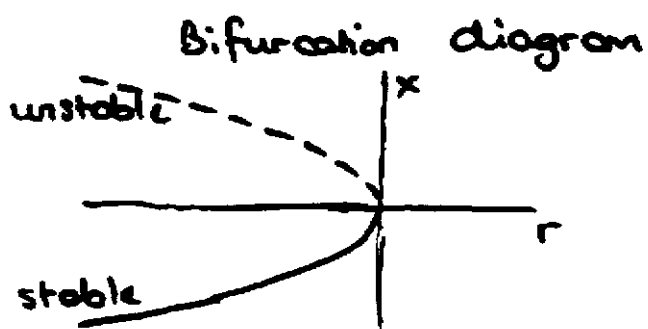
Linear stability analysis: $f'(x^*) = 2x^*$,

$x^* = -\sqrt{-r}$: $f'(x^*) < 0$ stable

$x^* = +\sqrt{-r}$: $f'(x^*) > 0$ unstable

Bifurcation at $r=0$ (of fixed point at $x=0$)

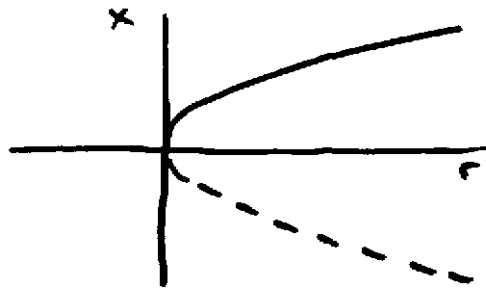
As r increases through 0, two fixed points approach each other, coalesce and vanish



(fixed points as function of bifurcation parameter)

Similarly:

$$\dot{x} = r - x^2$$

fixed points $x = \pm\sqrt{r}$ for $r \geq 0$ 

- a pair of fixed points created as r increases through 0.

Bifurcation: split into two branches of fixed points

Names: Saddle-node
Turning point
Fold
"Blue sky" } bifurcation

Note: the "prototypical examples"

and

$$\dot{x} = r + x^2$$

$$\dot{x} = r - x^2$$

are equivalent under the change of variables

$$x \rightarrow -x, \quad r \rightarrow -r$$

(sufficient to consider $\dot{x} = r - x^2$)

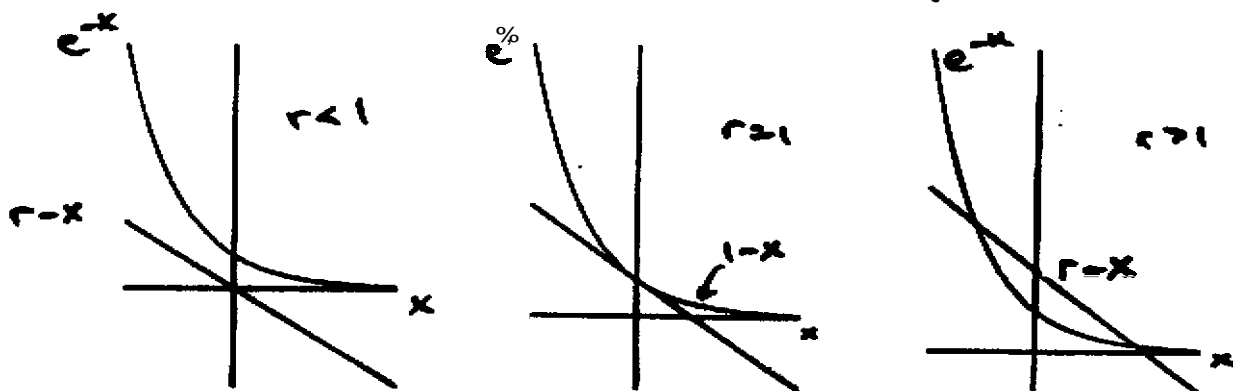
Example: $\dot{x} = r - x - e^{-x}$

3.4

- show this undergoes a saddle-node bifurcation; what is r_c ?

Fixed points: $r - x^* - e^{-x^*} = 0$ transcendental equation for $x^*(r)$.

Graphical approach: plot $r-x$, e^{-x} simultaneously, look for intercepts.



Bifurcation point (x^*, r_c) :

1. $f(x^*, r_c) = 0$ fixed point
2. Curves have same slope i.e. $-1 = -e^{-x}$
(fixed points coalesce: x^* is double zero)
i.e. $\frac{\partial f}{\partial x} \Big|_{x^*, r_c} = 0$.

From 2: $e^{-x^*} = 1 \Rightarrow x^* = 0$

1. $r_c - x^* - e^{-x^*} \Rightarrow r_c = 1$.

Bifurcation $(x^*, r_c) = (0, 1)$

Expand near x^*, r_c :

$$\begin{aligned}
 f(x, r) &= r - x - e^{-x} = 1 + (r-1) - x \\
 &\quad - \left(1 - x + \frac{1}{2}x^2 - \frac{1}{3!}x^3 + \dots \right) \\
 &= (r-1) - \frac{1}{2}x^2 + \mathcal{O}(x^3) \\
 &\quad \uparrow \\
 &\quad \frac{1}{3!}x^3 - \frac{1}{4!}x^4 + \dots
 \end{aligned}$$

$$\dot{x} = f(x, r) = r - x - e^{-x}$$

3.5

$$= (r-1) - \frac{1}{2}x^2 + \mathcal{O}(x^3)$$

same form as $\dot{X} = R - X^2$

In fact: $X = \frac{1}{2}x$, $R = \frac{1}{2}(r-1)$

$$\Rightarrow x = 2X, \quad r = 2R + 1$$

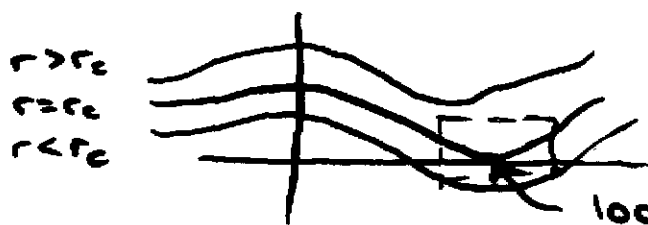
$$\Rightarrow 2\dot{X} = 2R - \frac{1}{2}(2X)^2 + \dots$$

$$\Rightarrow \boxed{\dot{X} = R - X^2} + \dots$$

normal form for saddle-node bifurcation
("generic")

Normal form: representative of all saddle-node bifurcations

(close to bifurcation point, dynamics look like $\dot{x} = r \pm x^2$)



locally $f(x)$ looks parabolic

Algebraically: Taylor expand near bifurcation point x^*, r_c

$$\begin{aligned} \dot{x} = f(x, r) = & f(x^*, r_c) + (x - x^*) \left. \frac{\partial f}{\partial x} \right|_{(x^*, r_c)} + (r - r_c) \left. \frac{\partial f}{\partial r} \right|_{(x^*, r_c)} \\ & + \frac{1}{2} (x - x^*)^2 \left. \frac{\partial^2 f}{\partial x^2} \right|_{(x^*, r_c)} + \dots \end{aligned}$$

At bifurcation point: $f(x^*, r_c) = 0$

(x^* is a fixed point)

$$\left. \frac{\partial f}{\partial x} \right|_{(x^*, r_c)} = 0$$

(tangency condition:
 x^* is not simple zero
 $f(x)$ is tangent to 0 at x^*)

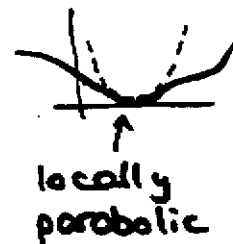
Bifurcation of fixed point at x^*, r_c : $f(x^*, r_c) = 0$

$$\frac{\partial f}{\partial x}(x^*, r_c) = 0$$

$$\Rightarrow \dot{x} = (r - r_c) \frac{\partial f}{\partial r} \Big|_{(x^*, r_c)} + \frac{1}{2} (x - x^*)^2 \frac{\partial^2 f}{\partial x^2} \Big|_{(x^*, r_c)} + \dots$$

Also, generically (in absence of special symmetries ...)
 expect

$$\frac{\partial f}{\partial r}(x^*, r_c) \neq 0, \quad \frac{\partial^2 f}{\partial x^2}(x^*, r_c) \neq 0$$



Let $a = \frac{\partial f}{\partial r}(x^*, r_c)$, $b = \frac{1}{2} \frac{\partial^2 f}{\partial x^2}(x^*, r_c)$:

$$\dot{x} = a(r - r_c) + b(x - x^*)^2 + \dots$$

Rescale:

$$\left. \begin{aligned} X &= -b(x - x^*) \\ R &= -ab(r - r_c) \end{aligned} \right\} \Rightarrow$$

$$\dot{X} = R - X^2 + \dots$$

normal form for saddle-node bifⁿ.

Normal form theory

- can systematically eliminate higher-order terms by near-identity coordinate changes

eg. $\dot{x} = r - x^2 + ax^3 + \mathcal{O}(x^4)$, $|x| \ll 1, r \neq 0$

- define $x = X + bX^4$

- choose b to eliminate cubic term - get $\dot{X} = r - X^2 + \mathcal{O}(X^4)$

$$\Rightarrow X = x - bX^4 = x - b(x - bX^4)^4 = x - bx^4 + \mathcal{O}(x^7)$$

$$\dot{X} = (1 - 4bx^3 + \dots)\dot{x} = (1 - 4bx^3 + \dots)(r - x^2 + ax^3 + \dots)$$

$$= (1 - 4b(X + bX^4)^3 + \dots)(r - (X + bX^4)^2 + a(X + bX^4)^3 + \dots)$$

$$= r - X^2 + \underbrace{(a - 4b)}_0 X^3 + \mathcal{O}(X^4)$$

Choose $b = \frac{a}{4r}$

Summary: conditions for saddle-node bifurcation of $\dot{x} = f(x, r)$:

$$\text{At } (x^*, r_c) \quad f = 0, \quad \frac{\partial f}{\partial x} = 0; \quad \frac{\partial f}{\partial r} \neq 0, \quad \frac{\partial^2 f}{\partial x^2} \neq 0.$$

An alternative perspective: (continuous) dependence of zeros on r
 Equilibria of $\dot{x} = f(x, r) \Leftrightarrow$ zeros of f : $f(x, r) = 0$.

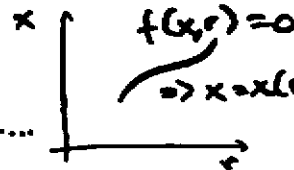
Suppose x_0 is a fixed point for a given r_0 .
 Then the equation $f(x, r) = 0$ defines a unique function $x^*(r)$ of r implicitly in some neighborhood containing r_0 (a continuous, single-valued function, satisfying $f(x^*(r), r) = 0$) provided $\frac{\partial f}{\partial x} \neq 0$.

\Rightarrow bifurcations of fixed points require $f = 0$ and $\frac{\partial f}{\partial x} = 0$.

Idea:

$$f(x^*, r) = \underbrace{f(x_0, r_0)}_{=0} + (x^* - x_0) \left. \frac{\partial f}{\partial x} \right|_{(x_0, r_0)} + (r - r_0) \left. \frac{\partial f}{\partial r} \right|_{(x_0, r_0)} + \dots$$

want $\rightarrow 0$

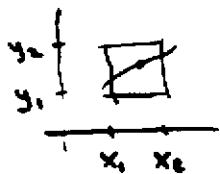


- can solve for $x^* = x^*(r)$ provided $\frac{\partial f}{\partial x} \neq 0$.

Implicit Function Theorem:

Assume $g(x_0, y_0) = 0$, $\frac{\partial g}{\partial y}(x_0, y_0) \neq 0$, and that $\frac{\partial g}{\partial x}$, $\frac{\partial g}{\partial y}$

are continuous. Then there exists a rectangle $R = [x_1, x_2] \times [y_1, y_2]$ containing (x_0, y_0) st. for each x , $x_1 \leq x \leq x_2$, the equation $g(x, y) = 0$ determines a unique $y = h(x)$ with $y_1 \leq y \leq y_2$ satisfying $y_0 = h(x_0)$ and $g(x, h(x)) = 0$ for $x \in [x_1, x_2]$, where $h(x)$ is continuous and has continuous derivative.



Transcritical Bifurcation

often a fixed point exists for all values of the parameter r

$$\dot{x} = f(x, r) \quad : \quad \text{fixed point } x^*(r), \text{ all } r$$

$$f(x^*, r) = 0 \quad (\Rightarrow) \quad \frac{\partial f}{\partial x}(x^*, r) = 0$$

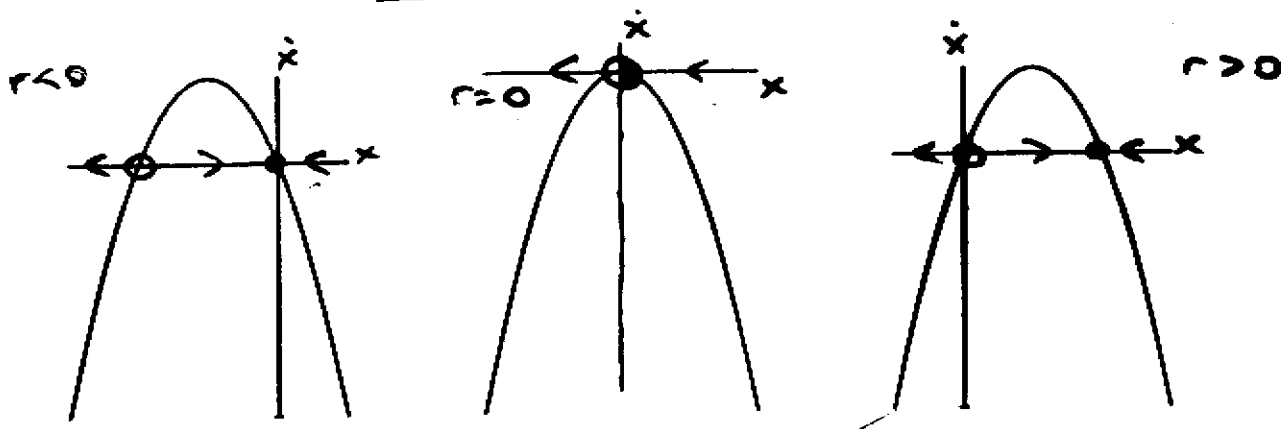
eg logistic model $\dot{N} = rN(1 - \frac{N}{K})$: $N=0$ is always a fixed point

- but change of stability

Normal form :

$$\dot{x} = rx - x^2$$

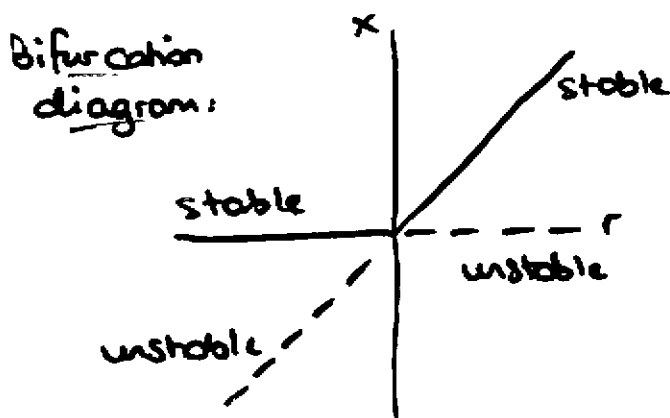
fixed points $x^* = 0, r$



$x^* = 0$ stable
 $x^* = r$ unstable

$x^* = 0$ half-stable

$x^* = 0$ unstable
 $x^* = r$ stable



Exchange of stabilities

Normal form:

$$\dot{x} = rx - x^2 + \dots$$

Local analysis near (x^*, r_c) :

$$\dot{x} = f(x, r) = f(x^*, r_c) + (x - x^*) \left. \frac{\partial f}{\partial x} \right|_{(x^*, r_c)} + (r - r_c) \left. \frac{\partial f}{\partial r} \right|_{(x^*, r_c)}$$

$$+ \frac{1}{2} (x - x^*)^2 \left. \frac{\partial^2 f}{\partial x^2} \right|_{(x^*, r_c)} + (x - x^*)(r - r_c) \left. \frac{\partial^2 f}{\partial x \partial r} \right|_{(x^*, r_c)} + \frac{1}{2} (r - r_c)^2 \left. \frac{\partial^2 f}{\partial r^2} \right|_{(x^*, r_c)} + \dots$$

eg $\dot{x} = r \ln x + x - 1$ $x^* = 1$ is a fixed point for all r

Analysis near $x=1$:

$$x = 1 + u$$

$$(|u| \ll 1)$$

$$\begin{aligned} \Rightarrow \dot{u} = \dot{x} &= r \ln x + x - 1 = r \ln(1+u) + (1+u) - 1 \\ &= r \left[u - \frac{1}{2}u^2 + \frac{1}{3}u^3 - \frac{1}{4}u^4 + \dots \right] + u \\ &= (r+1)u - \frac{1}{2}ru^2 + \mathcal{O}(u^3) \end{aligned}$$

Transcritical bifurcation at $r_c = -1$. no R dependence

Put into normal form - need $\dot{x} = R X - X^2 + \dots$

-rescale u to remove coefficient of u^2 :

$$u = a v$$

$$\begin{aligned} \Rightarrow \dot{v} &= \frac{1}{a} \dot{u} = \frac{1}{a} \left[(r+1)(av) - \frac{1}{2}r(av)^2 + \mathcal{O}(v^3) \right] \\ &= (r+1)v - \frac{1}{2}arv^2 + \mathcal{O}(v^3) \end{aligned}$$

$$\text{-set } \frac{1}{2}ar = 1 \Rightarrow a = \frac{2}{r}$$

$$\text{Then } \dot{v} = (r+1)v - v^2 + \mathcal{O}(v^3)$$

$$\text{Now let } R = r+1, X = v \quad (\Rightarrow X = \frac{1}{a}u = \frac{r}{2}(x-1))$$

$$\Rightarrow \boxed{\dot{X} = R X - X^2} + \mathcal{O}(X^3)$$

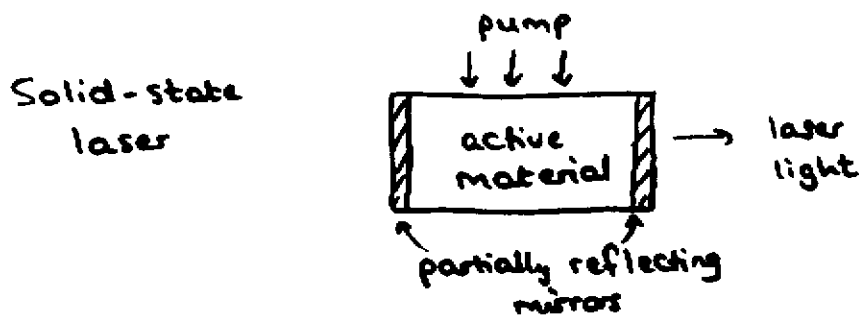
normal form

For $R \neq 0$, we can successively eliminate higher-order terms by near identity changes of variables $y = X + bX^k$

Summary: Transcritical bifurcation of $\dot{x} = f(x, r)$:

$$\text{At } (x^*, r_c) \\ f = 0, \quad \frac{\partial f}{\partial x} = 0, \quad \frac{\partial f}{\partial r} = 0, \quad \frac{\partial^2 f}{\partial x^2} \neq 0, \quad \frac{\partial^2 f}{\partial x \partial r} \neq 0$$

Laser Threshold



Atoms emit photons via

- spontaneous emission (incoherent)
- stimulated emission (coherent)

Beyond a certain pumping threshold, atoms oscillate in phase - laser. (self-organizing)

Simplified model: $n(t)$ - no. of coherent photons in laser field
 $N(t)$ - no. of excited atoms

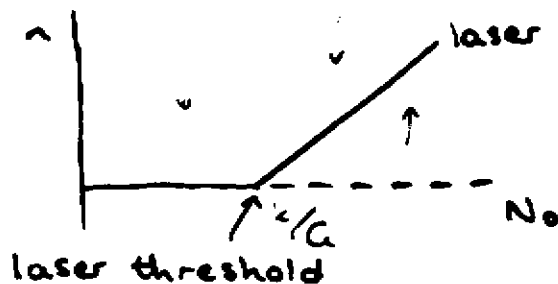
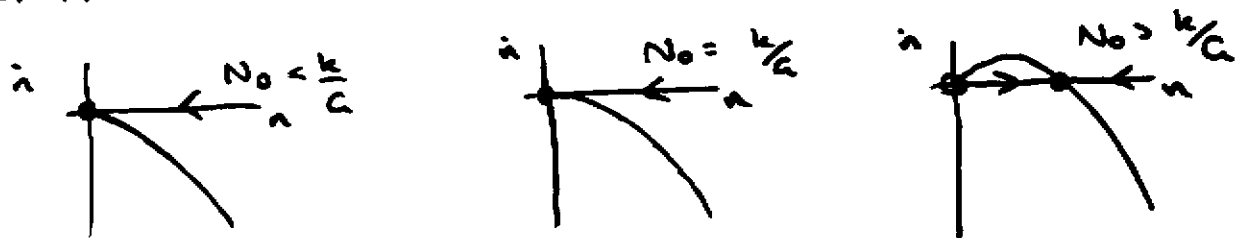
$$\dot{n} = \text{gain} - \text{loss} = G n N - k n$$

\uparrow gain coefficient \uparrow loss coefficient: rate of escape of photons through mirror

$$N(t) = N_0 - \alpha n(t)$$

\uparrow pump \uparrow rate of stimulated emission: atoms drop to ground state

$$\Rightarrow \dot{n} = G n (N_0 - \alpha n) - k n = (G N_0 - k) n - G \alpha n^2$$

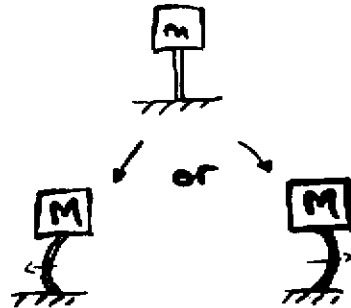


$n^* = 0$ undergoes a transcritical bifurcation at $N_0 = \frac{G}{k}$

Pitchfork Bifurcation

Bifurcation in the presence of symmetry (eg left-right)

$$f(-x, r) = -f(x, r) \quad (\text{odd})$$



$\Rightarrow \dot{x} = f(x, r)$ is invariant under $x \rightarrow -x$.

Consequences: $x^* = 0$ is always a fixed point $f(0, r) = 0$, all r
 $\Rightarrow \frac{\partial^k f}{\partial x^k} \Big|_{(x^*, r_c)} = 0, k \geq 1$

$$\frac{\partial^2 f}{\partial x^2} \Big|_{(x^*, r_c)} = \frac{\partial^3 f}{\partial x^3} \Big|_{(x^*, r_c)} = \dots = 0$$

(and $f(x^*, r_c) = \frac{\partial f}{\partial x} \Big|_{(x^*, r_c)} = 0$: bifurcation at $(x^*, r_c), x^* = 0$)

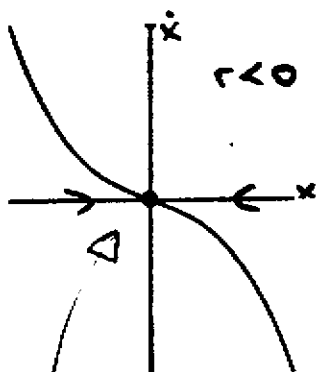
$$\Rightarrow \dot{x} = f(x, r) = (x - x^*)(r - r_c) \frac{\partial^2 f}{\partial x \partial r} \Big|_{(x^*, r_c)} + \frac{1}{3!} (x - x^*)^3 \frac{\partial^3 f}{\partial x^3} \Big|_{(x^*, r_c)} + \dots$$

Two types: supercritical, subcritical (sign of $\frac{\partial^3 f}{\partial x^3}$)

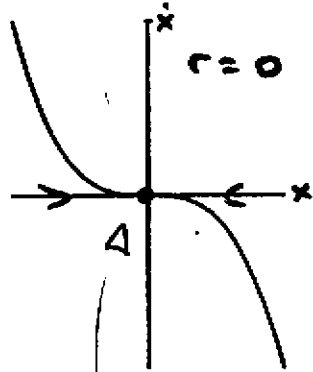
Supercritical Pitchfork Bifurcation

Normal form

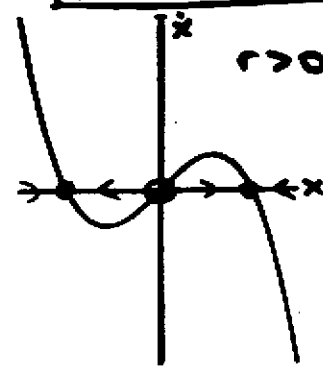
$$\dot{x} = rx - x^3$$



$x^* = 0$ linearly stable
exponential decay

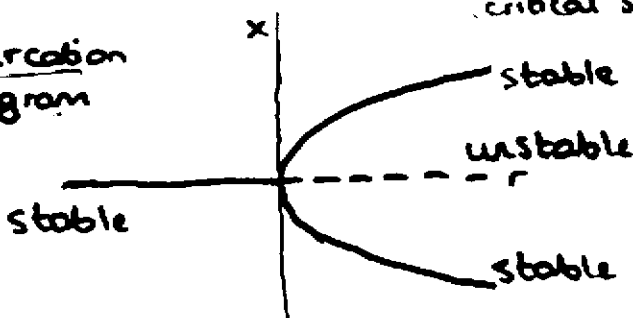


$x^* = 0$ algebraic decay
 $x(t) \sim t^{-1/2}$
critical slowing down



$x^* = 0$ unstable
 $x^* = \pm \sqrt{r}$ stable

Bifurcation diagram

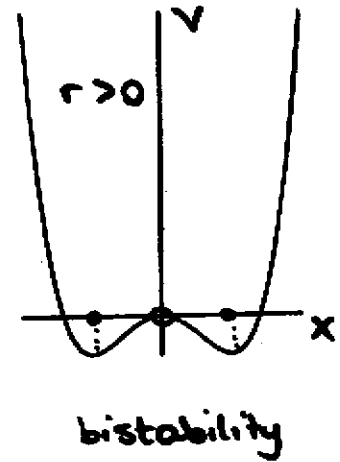
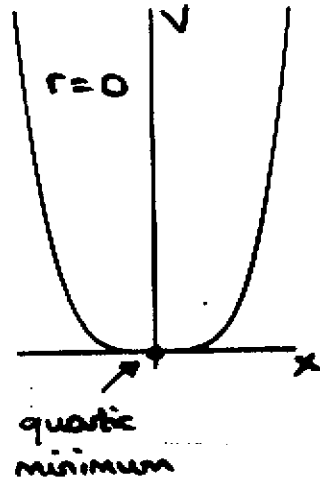
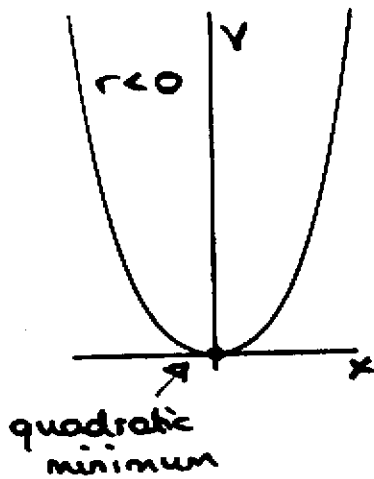


"supercritical" pitchfork bifurcation

($r > 0$: $x^* = 0$ unstable
stable nontrivial fixed points created)

Potential: $\dot{x} = rx - x^3 = -\frac{\partial V}{\partial x}$

$\Rightarrow V(x) = -\frac{1}{2}rx^2 + \frac{1}{4}x^4$

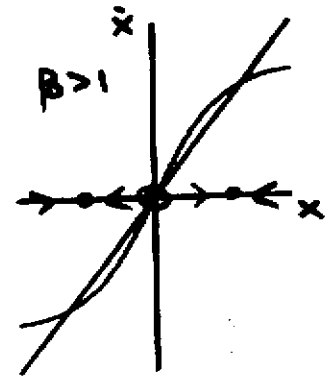
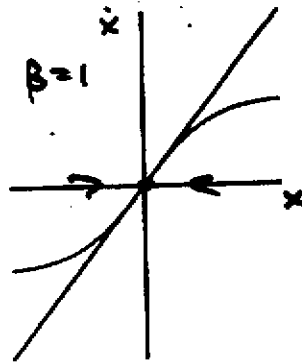
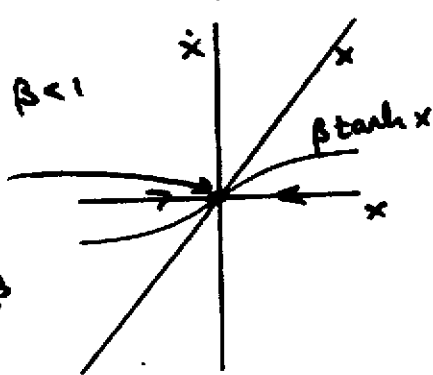


eg $\dot{x} = -x + \beta \tanh x$

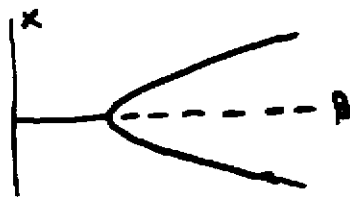
$x^* = 0$ - fixed point for all β
 Symmetry $x \rightarrow -x$ - expect pitchfork bifurcation

Fixed points:
 $x^* = \beta \tanh x^*$

slope of $\beta \tanh x$
 at $x=0$:
 $\beta \operatorname{sech}^2 0 = \beta$



Bifurcation diagram:
 supercritical pitchfork



$x^* = \beta \tanh x^*$:
 difficult to solve for $x^*(\beta)$
 (Newton)
 - plot $\beta = \frac{x^*}{\tanh x^*}$
 (parametric)

("forward" bifurcation
 "soft / safe")

related to second-order / continuous phase transitions)

eg ferromagnetism

Phase transitions

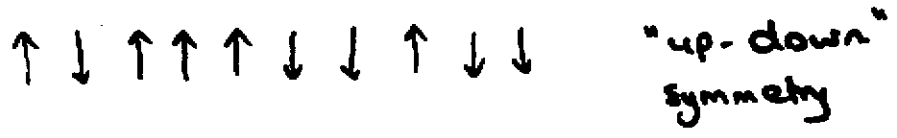
may be modelled by equations such as

$$\dot{x} = -x + \beta \tanh x$$

eg Ferromagnetism

- β related to magnetization
- $1/\beta$ related to temperature

Simple model: spins on a 1-d lattice (Ising model)

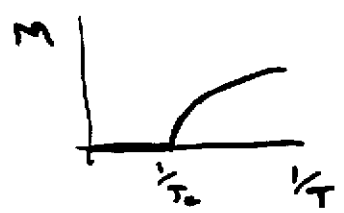


At high temperature ($\beta < 1$) disorder,
 random alignment of spins - zero average magnetization

At low temperature ($\beta > 1$) spontaneous order,
 alignment of spins - nonzero magnetization

- phase transition at critical temperature T_c .
- symmetry-breaking: ordered state has lower symmetry (either up or down)

Continuous phase transition:
 magnetization increases continuously from zero for $T < T_c$ (no jump)



Supercritical pitchfork bifurcation: $\dot{x} = rx - x^3$

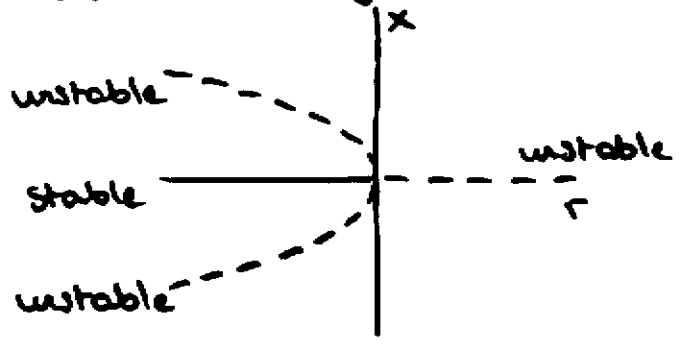
- cubic term is stabilizing
- nontrivial fixed points for $r > r_c$.

Subcritical Pitchfork Bifurcation

$$\dot{x} = rx + x^3$$

- cubic term is destabilizing

Bifurcation diagram



"subcritical": $r > 0$: $x^* = 0$ unstable

nontrivial fixed points exist below bifurcation, for $r < 0$

nonzero fixed points:

$$x^* = \pm \sqrt{-r}, r < 0$$

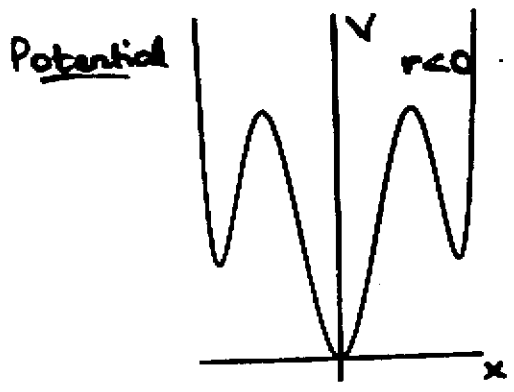
Note: $\dot{x} \sim x^3$ for large x : blow-up in finite time

- need a stabilizing higher-order term. $-x^5$

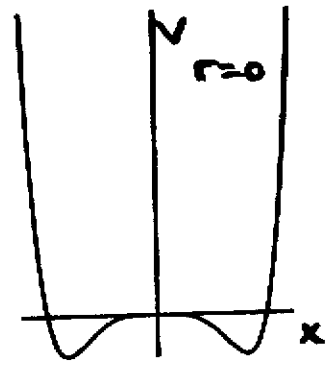
Canonical example:

$$\dot{x} = rx + x^3 - x^5$$

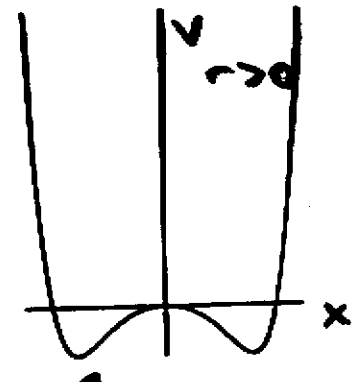
(respecting symmetry $x \rightarrow -x$)



3 stable, 2 unstable

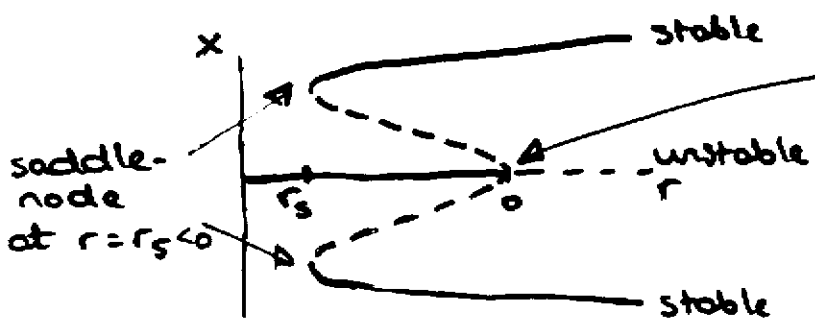


2 stable, 1 unstable at $x^* = 0$



$$V(x) = -\frac{1}{2}rx^2 - \frac{1}{4}x^4 + \frac{1}{6}x^6$$

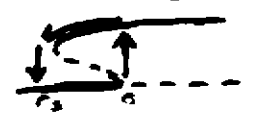
"backward/inverted" bifurcation
"hard/dangerous"
first-order/discontinuous phase transitions



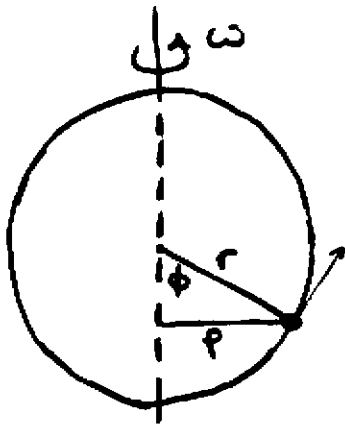
stable large-amplitude branches for $r > r_s$

Note: • Bistability $r_s < r < 0$ - two qualitatively different stable states: origin locally, not globally stable

• Jumps and Hysteresis as r is varied
- lack of reversibility



Overdamped bead on a Rotating Hoop



rigid hoop rotating about vertical

- tangential velocity $r \dot{\phi}$ ↗
- forces: gravitational mg ↓
- centrifugal $m\rho\omega^2$ →
- frictional $b\dot{\phi}$ ↙
- left-right symmetry

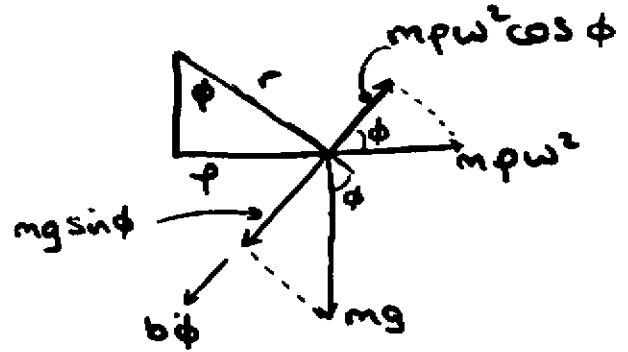
Balance of tangential forces:

$$\rho = r \sin \phi$$

Newton's Law:

$$m r \ddot{\phi} = -b \dot{\phi} - mg \sin \phi + m r \omega^2 \sin \phi \cos \phi$$

invariant under $\phi \rightarrow -\phi$



Second-order ODE - can we neglect $m r \ddot{\phi}$ term?

Assume (for now) $|m r \ddot{\phi}| \ll |b \dot{\phi}|$

$$\begin{aligned} \Rightarrow b \dot{\phi} &= m r \omega^2 \sin \phi \cos \phi - mg \sin \phi \\ &= mg \sin \phi \left(\frac{r \omega^2}{g} \cos \phi - 1 \right) \end{aligned}$$

Fixed points: $\sin \phi = 0 \Rightarrow \phi^* = 0$ (bottom)
 $\phi^* = \pi$ (top)

If $\gamma \equiv \frac{r \omega^2}{g} > 1$, two additional fixed points

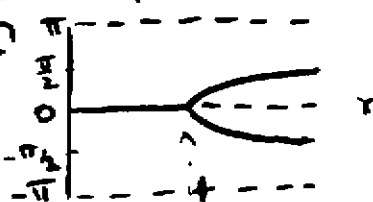
$$\cos \phi^* = 1/\gamma = g/r\omega^2$$

(note: $\gamma \rightarrow \infty \Rightarrow \phi^* \rightarrow \pm \pi/2$)

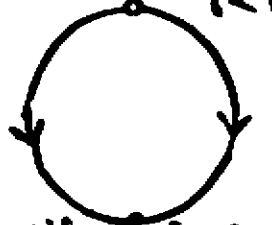
Condition for additional equilibria:

$$\omega > \omega_{crit} = \sqrt{g/r}$$

supercritical pitchfork bifurcation at $\gamma = 1$

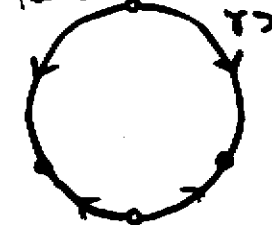


slow rotation $\gamma < 1$



centrifugal force weak

fast rotation $\gamma > 1$



centrifugal force balances gravity

symmetry-broken solutions

Dimensional Analysis and Scaling

When can we neglect $m r \ddot{\phi}$? (what is "small"?)

$m \rightarrow 0$ is not appropriate - ignores gravitational and centrifugal forces.

Scaling and Nondimensionalization :

- estimate typical / characteristic scales of the dependent variables
- estimate characteristic time (or length) scales; relative to these scales, derivatives are $\mathcal{O}(1)$
- reduce the number of relevant parameters to dimensionless groups (pure numbers) which determine dynamics
- there may be more than one choice of scales, different nondimensionalizations, appropriate in different regions

In dimensionless system - units are unimportant
- "large" and "small" have a definite meaning

Nondimensionalize - (express equation in dimensionless form)

ϕ : in radians (already a pure number)

Characteristic time scale T - new dimensionless time $\tau = \frac{t}{T}$

$$\frac{d}{dt} = \frac{d}{d\tau} \frac{d\tau}{dt} = \frac{1}{T} \frac{d}{d\tau} \quad (= d(\tau T))$$

$$\Rightarrow \dot{\phi} = \frac{d\phi}{dt} = \frac{1}{T} \frac{d\phi}{d\tau}, \quad \ddot{\phi} = \frac{d^2\phi}{dt^2} = \frac{1}{T^2} \frac{d^2\phi}{d\tau^2}$$

Substitute: $m r \ddot{\phi} = -b \dot{\phi} - m g \sin \phi + m r \omega^2 \sin \phi \cos \phi$

$$\Rightarrow \frac{m r}{T^2} \frac{d^2\phi}{d\tau^2} = - \frac{b}{T} \frac{d\phi}{d\tau} - m g \sin \phi + m r \omega^2 \sin \phi \cos \phi$$

Balance of forces - divide by force mg

$$\Rightarrow \left(\frac{r}{g T^2} \right) \frac{d^2\phi}{d\tau^2} = - \left(\frac{b}{mg T} \right) \frac{d\phi}{d\tau} - \sin \phi + \left(\frac{r \omega^2}{g} \right) \cos \phi \sin \phi$$

↑
dimensionless groups

Choice of natural time scale T :

- so terms on r.h.s. are comparable i.e. $\frac{b}{mgT} = \mathcal{O}(1)$

(since $\sin \phi = \mathcal{O}(1)$, and by assumption $\phi_{\tau}, \phi_{\tau\tau} = \mathcal{O}(1)$)

- choose $T = \frac{b}{mg}$

We can neglect $\frac{d^2\phi}{d\tau^2}$ term on l.h.s. (to get a first-order system

$$\text{if } \frac{r}{gT^2} = \frac{r}{g} \left(\frac{mg}{b}\right)^2 = \frac{rm^2g}{b^2} \ll 1$$

Define $\epsilon = \frac{r}{gT^2} = \frac{rm^2g}{b^2}$ (dimensionless)

Dimensionless formulation

$$\boxed{\epsilon \frac{d^2\phi}{d\tau^2} = -\frac{d\phi}{d\tau} - \sin \phi + \gamma \cos \phi \sin \phi}$$

(5 parameters \rightarrow 2 dimensionless group:
 m, g, r, b, ω ϵ, γ)

Overdamped limit

$$\epsilon \ll 1 \Leftrightarrow b^2 \gg rm^2g$$

("strong damping" / "small mass" made precise)

From dimensional analysis, we expect:

In overdamped limit $\epsilon \rightarrow 0$, the dynamics of the bead should be well-approximated by the first-order system

$$\frac{d\phi}{d\tau} = f(\phi) \equiv \sin \phi (\gamma \cos \phi - 1)$$

Paradox: Can $\frac{d\phi}{d\tau} = f(\phi)$ uniformly describe (up to $\mathcal{O}(\epsilon)$ corrections) the motion of the bead? No...

Second-order ODE $\phi'' = \tilde{f}(\phi, \phi')$ - specify 2 initial conditions $\phi(0), \phi'(0)$

First-order ODE $\phi' = f(\phi)$ - specify 1 initial condition $\phi(0)$
 - compute $\phi'(0) = f(\phi(0))$

In general, solution of $\phi' = f(\phi)$ cannot satisfy both conditions

Phase Plane Analysis

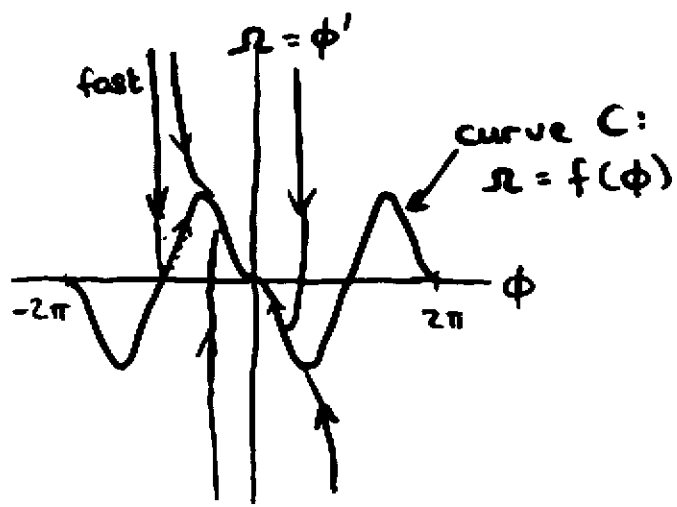
- interpret 2nd order ODE as a vector field in the plane:

$$\epsilon \frac{d^2\phi}{dt^2} = -\frac{d\phi}{dt} + f(\phi), \quad \epsilon \ll 1$$

Introduce $\Omega \equiv \phi' \equiv \frac{d\phi}{dt}$ ($\Rightarrow \epsilon \Omega' = \epsilon \phi'' = -\frac{\phi'}{\Omega} + f(\phi)$)

then
$$\begin{cases} \phi' = \Omega \\ \Omega' = \frac{1}{\epsilon} (f(\phi) - \Omega) \end{cases}$$

If $f(\phi) - \Omega$ is $\mathcal{O}(1)$, then Ω' is $\mathcal{O}(\frac{1}{\epsilon}) \gg 1$ i.e. Ω' is very large, so Ω changes rapidly, the phase point zaps towards $f(\phi) - \Omega = \mathcal{O}(\epsilon)$, then it evolves along $\Omega \approx f(\phi)$, i.e. according to $\phi' = f(\phi)$.



Typical trajectory:

- rapid initial transient on timescale ϵ
(dimensional: $T_{fast} = \epsilon T = \frac{m\tau}{b}$)
- cannot neglect $\epsilon \frac{d^2\phi}{dt^2}$
- slow drift along curve where $\phi' = f(\phi)$ on timescale 1
(dimensional: $T_{slow} = T = \frac{b}{mg}$)

Dynamics on fast timescale: $\sigma = \tau/\epsilon$

$$\Rightarrow \begin{cases} \frac{d\phi}{d\sigma} = \epsilon \Omega \\ \frac{d\Omega}{d\sigma} = f(\phi) - \Omega \end{cases} \Rightarrow \begin{cases} \phi \approx \text{constant} \\ \Omega \text{ decays exp. to } f(\phi) \end{cases}$$

Note: $\epsilon \rightarrow 0$ is a singular limit

(highest order derivative is lost)

Mathematical treatment: singular perturbation theory

eg boundary layers in fluid mechanics for "small viscosity" (dimensionless: high Reynolds number)

Imperfect Bifurcations

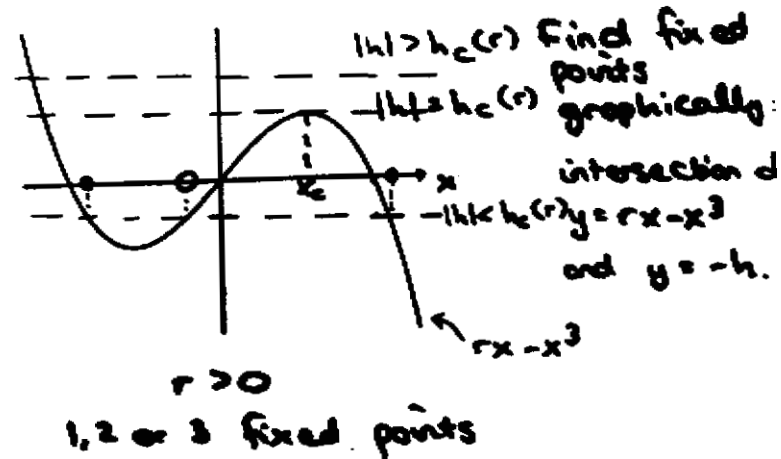
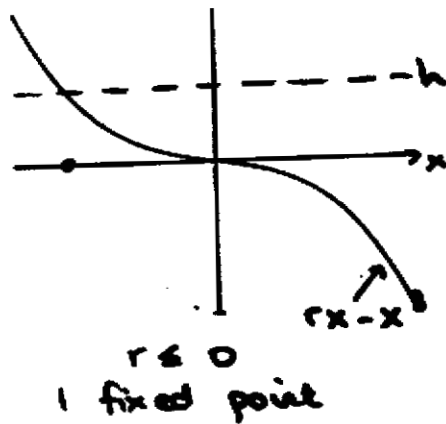
Symmetry $x \rightarrow -x$: pitchfork
 What if symmetry is approximate?

$$\dot{x} = h + rx - x^3 \quad (2 \text{ parameters})$$

↑ imperfection parameter

($h=0$: supercritical pitchfork bifurcation at $r=0$.)

Fix r , vary h :



$r > 0$: Critical value $h_c(r)$ (saddle-node bifurcation)
 - where $h = \text{const.}$ is tangent to $rx - x^3$:

$$\frac{\partial}{\partial x} (rx - x^3) = r - 3x^2 = 0 \Rightarrow x = \pm x_c = \sqrt{\frac{r}{3}}$$

$$\text{value at } x_c: h_c = rx_c - x_c^3 = r\sqrt{\frac{r}{3}} - \left(\sqrt{\frac{r}{3}}\right)^3 = \frac{2r}{3}\sqrt{\frac{r}{3}}$$

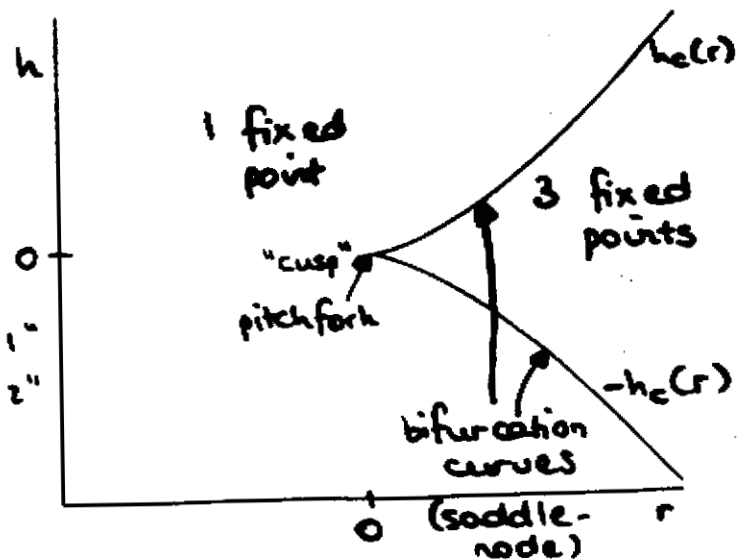
$$\text{Saddle-node at } h = \pm h_c(r) = \frac{2r}{3}\sqrt{\frac{r}{3}} : 27h^2 = 4r^3$$

Stability Diagram

(plot of types of behaviour,
 no. of fixed points in
parameter space)

$h \neq 0$: saddle-node "codimension 1"
 $h = 0, r = 0$: pitchfork "codimension 2"
 (need to tune 2 parameters)

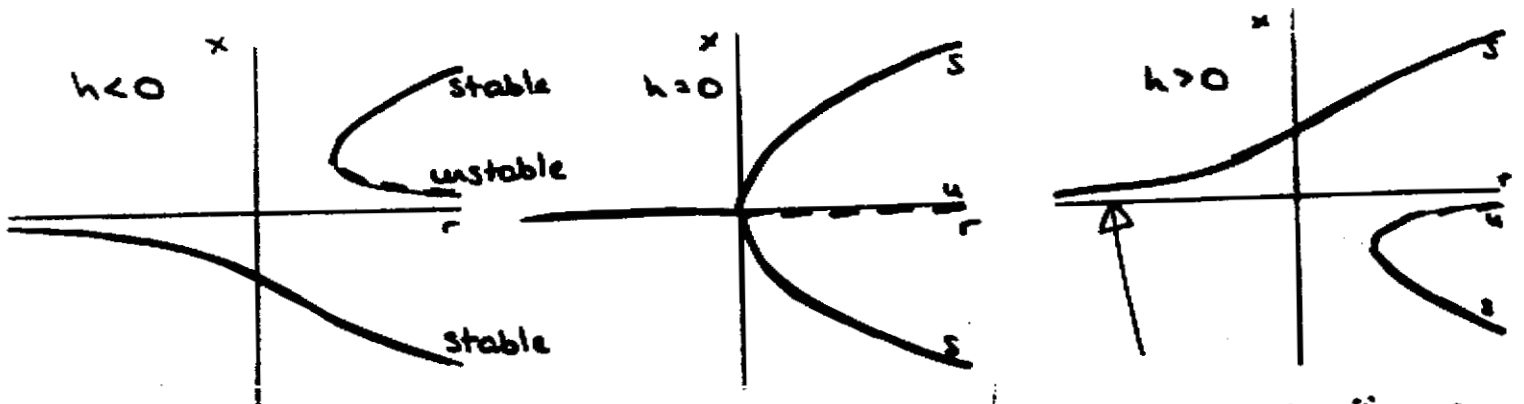
$(r, h) = (0, 0)$: cusp point
 (curves meet tangentially)



Bifurcation diagrams

Fix h : x^* as function of r

$$(r = \frac{x^3 - h}{x})$$

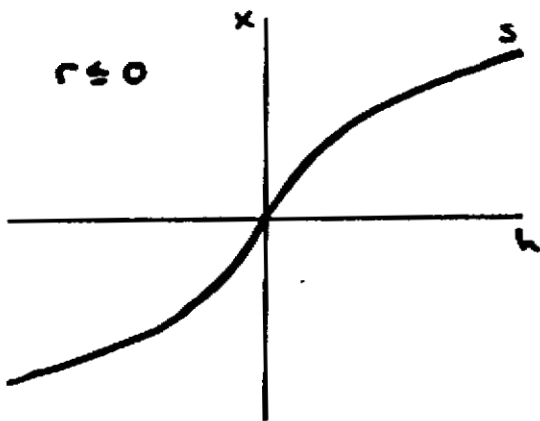


supercritical pitchfork bifurcation

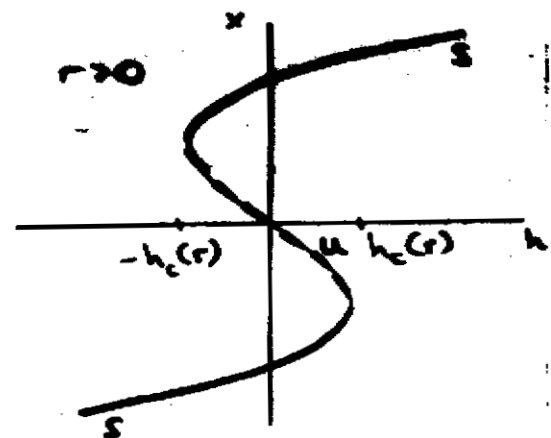
no sharp transition as r increases from $r < 0$ - stay on stable branch

Fix r : x^* as function of h

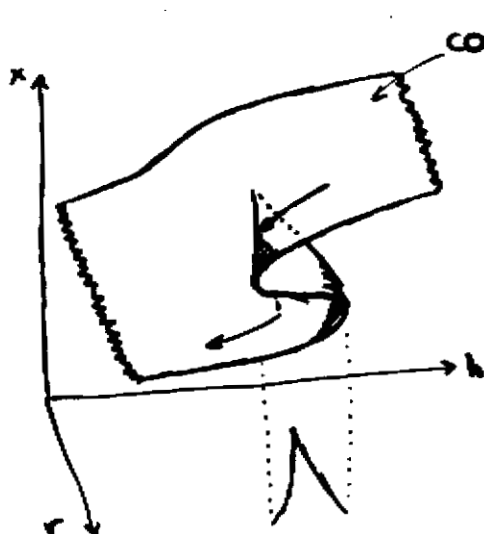
$$(h = -rx + x^3)$$



1 stable fixed point for each h



3 fixed points when $|h| < h_c(r)$

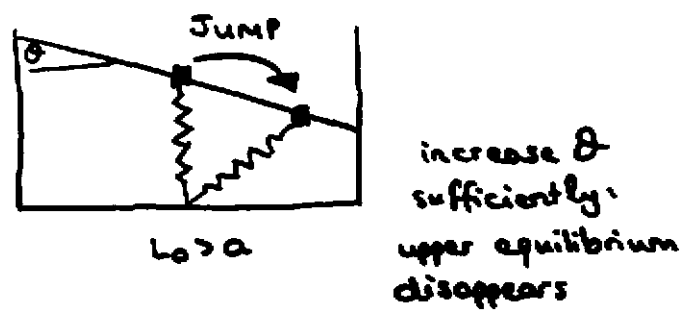
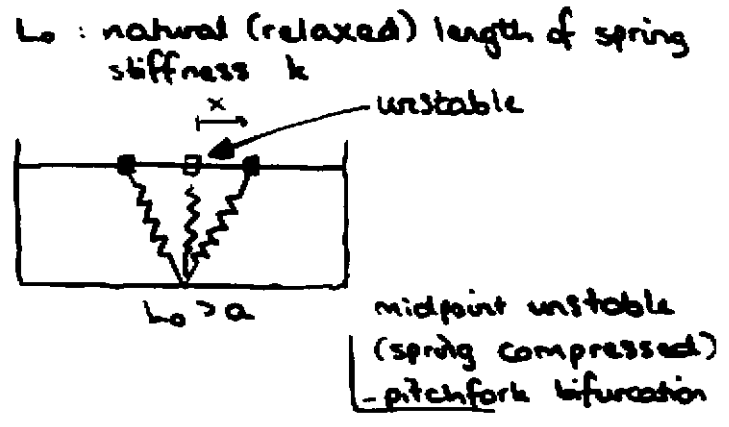
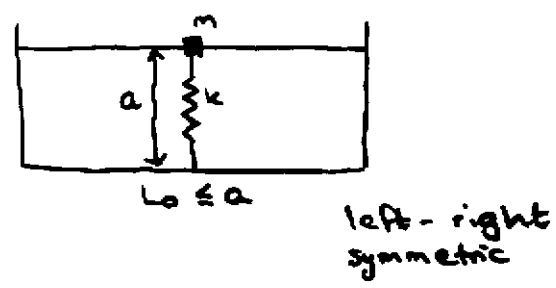


catastrophe surface

cusp catastrophe

Catastrophe: discontinuous change in the state of a system due to smooth change of parameters

eg Bead on a tilted wire



a : bifurcation parameter
 θ : imperfection parameter

Insect Outbreak

(Ludwig et al, 1978)

Spruce budworm attacks leaves of balsam fir

Budworm: fast timescale - characteristic doubling time \sim months

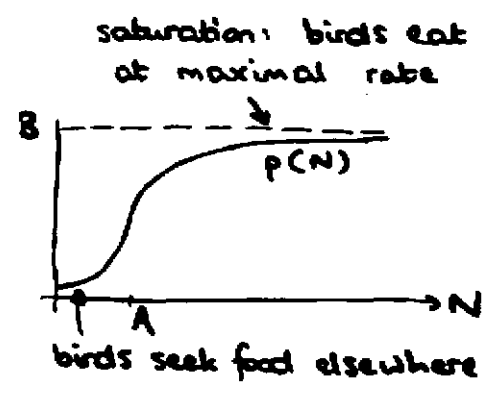
Fir trees: slow timescale - replace foliage \sim 7-10 yrs
- life span \sim 100-150 yrs

- view forest variables as "constant" parameters, not dynamic variables

Model:

$N(t)$ - budworm population

$$\frac{dN}{dt} = \underbrace{RN\left(1 - \frac{N}{K}\right)}_{\text{logistic: growth rate } R \text{ carrying capacity } K} - \underbrace{p(N)}_{\text{predation (by birds)}}$$



$$\frac{dN}{dt} = RN\left(1 - \frac{N}{K}\right) - p(N)$$

$p(N)$ - sigmoid function - models a "switch",
threshold A

- use
$$p(N) = B \cdot \frac{N^2}{A^2 + N^2}$$

$$\Rightarrow \dot{N} = RN\left(1 - \frac{N}{K}\right) - B \frac{N^2}{A^2 + N^2} \quad : 4 \text{ parameters } A, B, R, K > 0$$

Nondimensionalize!

K, A have units of N : different choices of nondimensionalization
- choose to put parameters into logistic part,
not into predation part :

$$x = \frac{N}{A} \quad (\text{and divide by } B)$$

$N = Ax$:

$$\Rightarrow \frac{A}{B} \frac{dx}{dt} = \frac{RA}{B} x \left(1 - \frac{A}{K} x\right) - \frac{x^2}{1+x^2}$$

Dimensionless parameters $r = \frac{RA}{B}$, $k = \frac{K}{A}$; time scale $\frac{A}{B}$ is $\tau = \frac{B}{A} t$; $\frac{dx}{dt} = \frac{A}{B} \frac{dx}{dt}$

\rightarrow Dimensionless system:

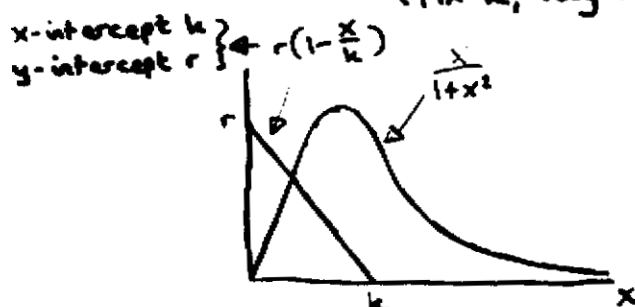
$$\boxed{\frac{dx}{d\tau} = rx\left(1 - \frac{x}{k}\right) - \frac{x^2}{1+x^2}} = f(x, r, k)$$

2 dimensionless parameters:
 $r, k > 0$

Fixed points:

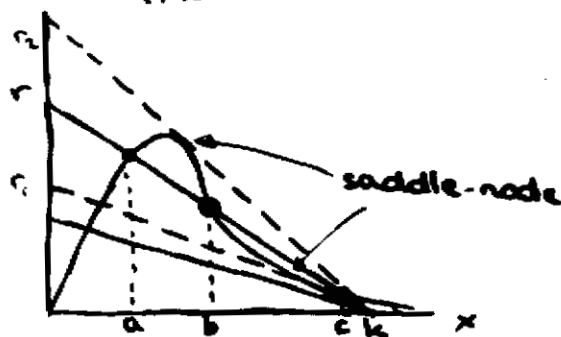
$x^* = 0$, always unstable $\left. \frac{\partial f}{\partial x} \right|_{x=0} = r > 0$ (small x :
low predation exponential growth)

$x \neq 0$: Graphical analysis:
(fix k , vary r)



small k : one (nontrivial) steady state

$$\left(1 - \frac{x}{k}\right) = \frac{x}{1+x^2}$$



large k : 1, 2 or 3 solutions

For sufficiently large k : saddle-node bifurcations

$$\text{at } \begin{cases} r = r_1(k) & (\text{between fixed points } b \text{ and } c) \\ r = r_2(k) & (\text{between fixed points } a \text{ and } b) \end{cases}$$

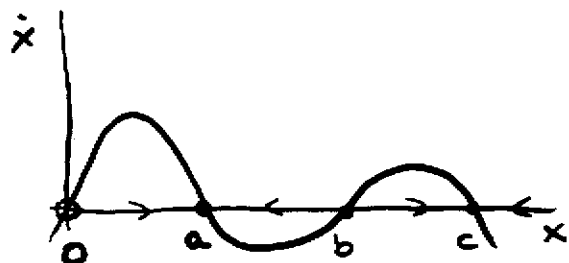
Stability: - alternates between stable and unstable

$$0 < a < b < c$$

$$\begin{matrix} u & s & u & s \\ \downarrow & \downarrow & \downarrow & \downarrow \\ a & b & c & \end{matrix}$$

stable equilibria: $x^* = a$: refuge

$x^* = c$: outbreak



Pest control: wish to keep budworm population at a , away from c

Initial conditions: $x(0) < b \Rightarrow x(t) \rightarrow a$
 $x(0) > b \Rightarrow x(t) \rightarrow c$ } $x^* = b$: threshold

If parameters change so r increases beyond $r_2(k)$:

outbreak triggered by saddle-node bifurcation of a and b

(due to hysteresis: if r decreases, population stays at c)

Saddle-node bifurcation curves:

require $r(1 - \frac{x}{k}) = \frac{x}{1+x^2}$ ① and $\frac{\partial}{\partial x} [r(1 - \frac{x}{k})] = \frac{\partial}{\partial x} [\frac{x}{1+x^2}]$

nontrivial fixed point

tangency (i.e. $\frac{\partial f}{\partial x} = 0, x \neq 0$)

$$\Rightarrow -\frac{r}{k} = \frac{1-x^2}{(1+x^2)^2}$$
 ②

Substitute ② in ①:

$$r = \frac{r}{k} x + \frac{x}{1+x^2} = \frac{x^2-1}{(1+x^2)^2} x + \frac{x}{1+x^2} \Rightarrow r = \frac{2x^3}{(1+x^2)^2}$$
 ③

Substitute ③ in ②:

$$k = -r \frac{(1+x^2)^2}{1-x^2} = \frac{2x^3}{(1+x^2)^2} \frac{(1+x^2)^2}{x^2-1} \Rightarrow k = \frac{2x^3}{x^2-1}$$
 ④

parametric representation $(r(x), k(x))$ of bifurcation curves

Note: $k > 0 \Rightarrow x > 1$. ($N > A$)

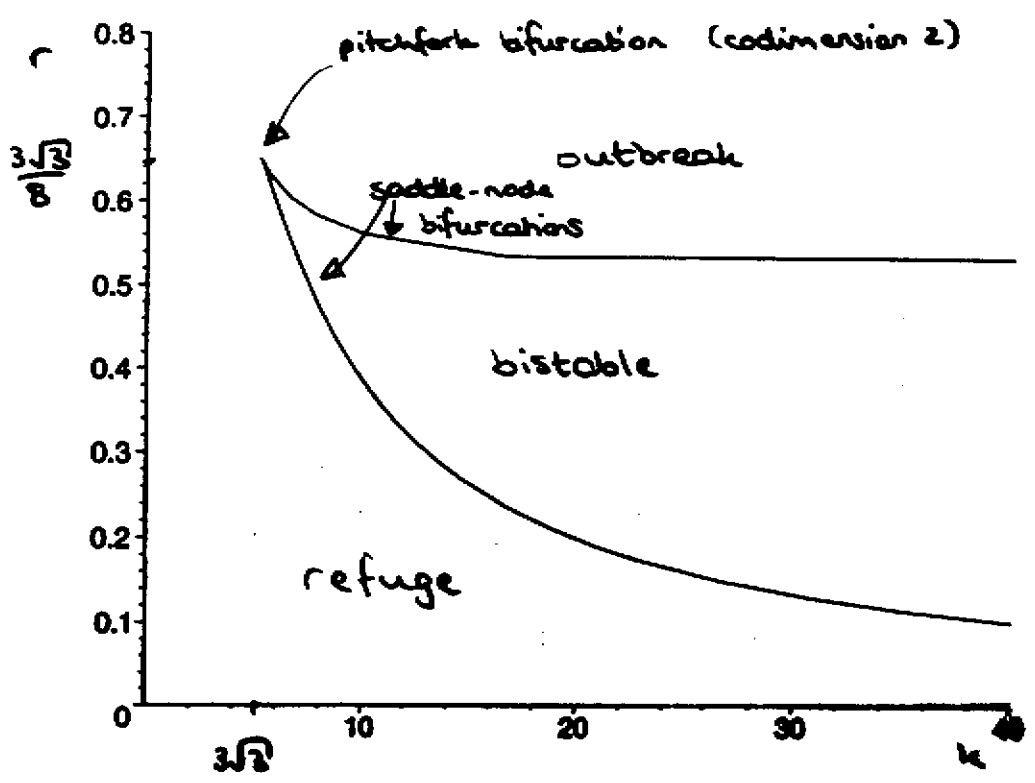
$$\frac{dr}{dx} = \dots = \frac{-2x^2(x^2-3)}{(1+x^2)^3}, \quad \frac{dk}{dx} = \frac{2x^2(x^2-3)}{(x^2-1)^2} \Rightarrow \text{max. of } r, \text{ min. of } k \text{ at } x = \sqrt{3}:$$

$$r_{\max} = \frac{3\sqrt{3}}{8}, \quad k_{\max} = 3\sqrt{3}$$

Bifurcation curves:
(parametric form)

$$\left. \begin{aligned} r(s) &= \frac{2s^3}{(1+s^2)^2} \\ k(s) &= \frac{2s^2}{s^2-1} \end{aligned} \right\} s > 1$$

Stability Diagram:



Biologically plausible parameter values?

Approximations:
neglected - tree dynamics
- spatial effects

S : average size of trees (total surface area of foliage in a stand)

Expect carrying capacity K , half-saturation parameter A to be proportional to foliage area

$$K = K'S, \quad A = A'S$$

\Rightarrow dimensionless parameters $r = \frac{RA}{B} = \frac{RA'}{B} S, \quad k = \frac{K}{A} = \frac{K'}{A'}$

As the forest grows, expect: r increases, k fixed

Young forest: $k \approx 300, r < 1/2$ - bistable

More mature forest: k increases - parameter drift to $r \geq 1$
- outbreak!

- fir trees die, birch trees take over, forest takes 50-100 yrs to recover